

# Stability analysis of a three-dimensional chemotaxis system

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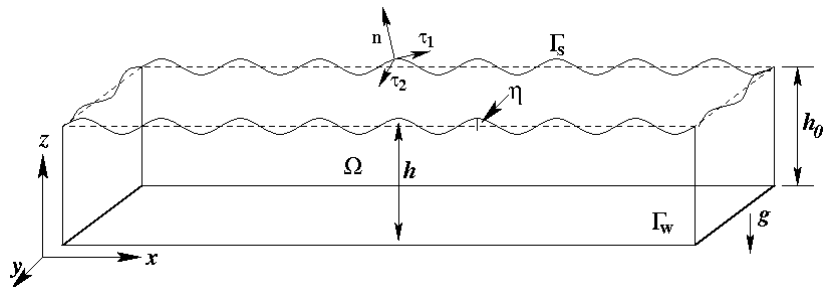


# Motivation



<https://tetrahymenaasset.vet.cornell.edu/science-modules/by-name/pattern-formation/>

# Introduction



**Figure 1:** Schematic diagram of a three-dimensional chemotaxis system with liquid-air interface  $\Gamma_s$ , where the oxygen concentration is equal to that of air, not crossed by bacteria. No-slip boundary condition is imposed at the container walls  $\Gamma_w$ .

## Governing Equations

The dimensional NS along with the KS equations are:

$$\nabla \cdot \mathbf{u} = 0, \quad (1a)$$

$$\rho (\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) + \nabla p - \mu \nabla^2 \mathbf{u} + \rho g = -n V_b g (\rho_b - \rho) \mathbf{k}, \quad (1b)$$

$$n_t + \nabla \cdot [\mathbf{u}n - D_b \nabla n + S_{dim} r(c) n \nabla c] = 0, \quad (1c)$$

$$c_t + \nabla \cdot (\mathbf{u}c - D_O \nabla c) = -n \kappa r(c). \quad (1d)$$

Boundary conditions prescribed on the deformed free-surface  $z = h(x, y, t)$ ,

$$\mathbf{n} \cdot \bar{\boldsymbol{\tau}} \cdot \mathbf{n} = -(\nabla \cdot \mathbf{n}) \sigma, \quad (1e)$$

$$\mathbf{t}_1 \cdot \bar{\boldsymbol{\tau}} \cdot \mathbf{n} = 0, \quad (1f)$$

$$\mathbf{t}_2 \cdot \bar{\boldsymbol{\tau}} \cdot \mathbf{n} = 0, \quad (1g)$$

$$S_{dim} n r(c) \nabla c \cdot \mathbf{n} = D_b \nabla n \cdot \mathbf{n}, \quad (1h)$$

$$c = c_{air}. \quad (1i)$$

## Governing Equations

$\mathbf{n} = \frac{(-h_x, -h_y, 1)}{N}$ , the unit outward normal vector,

$\mathbf{t}_1 = \frac{(1, 0, h_x)}{\sqrt{1+h_x^2}}$ ,  $\mathbf{t}_2 = \frac{(0, 1, h_y)}{\sqrt{1+h_y^2}}$ , the unit tangential vectors on the

interface and  $N = \sqrt{1+h_x^2+h_y^2}$ .

The kinematic boundary condition is

$$h_t = w - uh_x - vh_y, \quad (2a)$$

Other boundary conditions at the wall,

$$\mathbf{u} = 0, \quad \nabla n \cdot \mathbf{n} = 0, \quad \nabla c \cdot \mathbf{n} = 0, \quad \text{at } z = 0. \quad (2b)$$

## Governing Equations

Scaling:

$$(x, y) = L(x', y'), \quad z = h_0 z', \quad h = h_0 h', \quad n = \bar{n}_0 n', \quad c = c_{air} c',$$

$$t = \frac{h_0^2}{\varepsilon D_b} t', \quad p = \frac{\mu D_b}{\varepsilon h_0^2} p', \quad (u, v) = \frac{D_b}{h_0} (u', v'), \quad w = \frac{\varepsilon D_b}{h_0} w', \quad (3)$$

Dimensionless Navier-Stokes equation reads as

$$u_x + v_y + w_z = 0, \quad (4a)$$

$$\varepsilon (u_t + uu_x + vv_x + ww_x) + Pr_\tau p_x = Pr_\tau [\varepsilon^2 (u_{xx} + u_{yy}) + u_{zz}], \quad (4b)$$

$$\varepsilon (v_t + uv_x + vv_y + ww_y) + Pr_\tau p_y = Pr_\tau [\varepsilon^2 (v_{xx} + v_{yy}) + v_{zz}], \quad (4c)$$

$$\varepsilon^3 (w_t + uw_x + vw_y + ww_z) + Pr_\tau p_z = \varepsilon^2 Pr_\tau [\varepsilon^2 (w_{xx} + w_{yy}) + w_{zz}]$$

$$- \varepsilon Fr_\tau^{-2} - \varepsilon Pr_\tau Ra_\tau n, \quad (4d)$$

# Governing Equations

Dimensionless Keller-Segel equation reads as

$$\begin{aligned} \varepsilon(n_t + un_x + vn_y + wn_z) &= [\varepsilon^2(n_{xx} + n_{yy}) + n_{zz}] \\ &\quad - S_\tau r(c) \left( n[\varepsilon^2(c_{xx} + c_{yy}) + c_{zz}] \right. \\ &\quad \left. + [\varepsilon^2(c_x n_x + c_y n_y) + c_z n_z] \right), \end{aligned} \quad (5a)$$

$$\begin{aligned} \varepsilon(c_t + uc_x + vc_y + wc_z) &= -H_\tau r(c)n \\ &\quad + Le_\tau [\varepsilon^2(c_{xx} + c_{yy}) + c_{zz}]. \end{aligned} \quad (5b)$$

## Boundary conditions

Dimensionless boundary conditions at  $z = h(x, y, t)$ ,

$$\begin{aligned}
 p &+ \frac{\varepsilon^3 \left[ (1+\varepsilon^2 h_x^2) h_{yy} - 2\varepsilon^2 h_x h_y h_{xy} + (1+\varepsilon^2 h_y^2) h_{xx} \right]}{\text{Ca}\tau \left[ 1+\varepsilon^2 (h_x^2 + h_y^2) \right]^{\frac{3}{2}}} \\
 &= \frac{2\varepsilon^2 \left[ \varepsilon^2 \left( u_x h_x^2 + (u_y + v_x) h_x h_y + v_y h_y^2 \right) - (u_z + \varepsilon^2 w_x) h_x - (v_z + \varepsilon^2 w_y) h_y + w_z \right]}{\left[ 1+\varepsilon^2 (h_x^2 + h_y^2) \right]}, \quad (6a)
 \end{aligned}$$

$$\begin{aligned}
 \varepsilon^2 \left[ (u_y + v_x) h_y - 2(w_z - u_x) h_x + (v_z + \varepsilon^2 w_y) h_x h_y \right] \\
 = (1 - \varepsilon^2 h_x^2) (u_z + \varepsilon^2 w_x), \quad (6b)
 \end{aligned}$$

$$\begin{aligned}
 \varepsilon^2 \left[ (u_y + v_x) h_x - 2(w_z - v_y) h_y + (u_z + \varepsilon^2 w_x) h_x h_y \right] \\
 = (1 - \varepsilon^2 h_y^2) (v_z + \varepsilon^2 w_y), \quad (6c)
 \end{aligned}$$



## Boundary conditions

Dimensionless boundary conditions at  $z = h(x, y, t)$ ,

$$S_\tau r(c)n \left[ c_z - \varepsilon^2 (c_x h_x + c_y h_y) \right] = \left[ n_z - \varepsilon^2 (n_x h_x + n_y h_y) \right], \quad (7a)$$

$$c = 1. \quad (7b)$$

The kinematic boundary condition is

$$h_t + u h_x + v h_y = w. \quad (7c)$$

Other boundary conditions at  $z = 0$ ,

$$u = 0, \quad v = 0, \quad w = 0, \quad (7d)$$

$$n_z = \varepsilon^2 (n_x h_x + n_y h_y), \quad (7e)$$

$$c_z = \varepsilon^2 (c_x h_x + c_y h_y). \quad (7f)$$

## Dimensionless Parameters

Prandtl number,  $Pr_\tau = \frac{\nu}{D_b},$

Froude number,  $Fr_\tau = \frac{D_b}{\sqrt{gh_0^3}},$

Rayleigh number,  $Ra_\tau = \frac{gV_b\bar{n}_0(\rho_b-\rho)h_0^3}{D_b\mu},$

Chemotaxis sensitivity,  $S_\tau = \frac{S_{dim}c_{air}}{D_b},$

Chemotaxis head,  $H_\tau = \frac{\kappa\bar{n}_0h_0^2}{c_{air}D_b},$

Lewis number,  $Le_\tau = \frac{D_O}{D_b},$

Capillary number,  $Ca_\tau = \frac{\mu D_b}{\sigma h_0}.$

## Steady state solution

$$\rho(z) = \varepsilon \left( \frac{1}{Pr_\tau Fr_\tau^2} + Ra_\tau \right) (1-z), \quad (8a)$$

$$c(z) = 1 - \frac{2}{S_\tau} \ln \left( \frac{\cos\left(\frac{S_\tau}{2} A_1 z\right)}{\cos\left(\frac{S_\tau}{2} A_1\right)} \right), \quad (8b)$$

$$n(z) = \frac{S_\tau Le_\tau A_1^2}{2 H_\tau} \sec^2 \left( \frac{S_\tau}{2} A_1 z \right), \quad (8c)$$

where the unknown constant  $A_1$  is determined from the transcendental equation:  $\tan\left(\frac{S_\tau}{2} A_1\right) = \frac{H_\tau}{Le_\tau} \frac{1}{A_1}$ .

$$n(z) = 1 + \frac{S_\tau}{6} (3z^2 - 1) \frac{H_\tau}{Le_\tau} + \frac{S_\tau^2}{18} (1 - 3z^2 + 3z^4) \frac{H_\tau^2}{Le_\tau^2} + O\left(\frac{H_\tau}{Le_\tau}\right)^3$$

$$c(z) = 1 + \frac{1}{2} (z^2 - 1) \frac{H_\tau}{Le_\tau} + \frac{S_\tau}{24} (z^2 - 1)^2 \frac{H_\tau^2}{Le_\tau^2} + O\left(\frac{H_\tau}{Le_\tau}\right)^3$$

## Linear stability analysis

Perturb the field variables at the basic state:

$$\begin{aligned} \mathbf{u}(\mathbf{x}, t) &= \varepsilon \tilde{\mathbf{u}}(\mathbf{x}, t), & p(\mathbf{x}, t) &= p(z) + \varepsilon \tilde{p}(\mathbf{x}, t), \\ n(\mathbf{x}, t) &= n(z) + \varepsilon \tilde{n}(\mathbf{x}, t), & c(\mathbf{x}, t) &= c(z) + \varepsilon \tilde{c}(\mathbf{x}, t), \\ h(\mathbf{x}, t) &= 1 + \varepsilon \tilde{h}(\mathbf{x}, t). \end{aligned} \quad (9)$$

Eliminate of  $\tilde{p}$ ,  $\tilde{u}$ , and  $\tilde{v}$ , and then the governing equations can be expressed in terms of  $\tilde{w}$ ,  $\tilde{n}$ , and  $\tilde{c}$  only. Take the divergence of the linearized NS equations, *i.e.*,  $[\partial_x(x\text{-mom}) + \partial_y(y\text{-mom}) + \partial_z(z\text{-mom})]$  and use of the continuity equation will give

$$\nabla^2 \tilde{p} = (1 - \varepsilon^2) \left[ \frac{\varepsilon}{Pr} \tilde{w}_t - \varepsilon^2 \left( \tilde{w}_{xx} + \tilde{w}_{yy} \right) - \tilde{w}_{zz} \right] - \varepsilon Ra_\tau \tilde{n}_z. \quad (10)$$

## Linear stability analysis

Apply Laplacian operator on the z-component of the linearized NS equation and use (10) to eliminate the pressure.

$$\begin{aligned} & \varepsilon \left[ \varepsilon^2 \left( \tilde{w}_{xx} + \tilde{w}_{yy} \right) + \tilde{w}_{zz} \right]_t - Pr_\tau \left[ \varepsilon^4 \left( \tilde{w}_{xxxx} + \tilde{w}_{yyyy} \right) + \tilde{w}_{zzzz} \right] \\ & = -\varepsilon Pr_\tau Ra_\tau \left( \tilde{n}_{xx} + \tilde{n}_{yy} \right) + 2\varepsilon^2 Pr_\tau \left( \tilde{w}_{xxzz} + \tilde{w}_{yyzz} + \varepsilon^2 \tilde{w}_{xxyy} \right). \end{aligned} \quad (11)$$

Adding of  $\partial_z$ (z-mom) with the two-dimensional Laplacian operator of the linearized normal stress boundary condition and using (10) will give

$$\begin{aligned} & Pr_\tau \left[ 3\varepsilon^2 \left( \tilde{w}_{xx} + \tilde{w}_{yy} \right) + \tilde{w}_{zz} \right]_z - \varepsilon \tilde{w}_{zt} \\ & = \varepsilon^3 \frac{Pr_\tau}{Ca_\tau} \left( \tilde{\eta}_{xxxx} + 2\tilde{\eta}_{xxyy} + \tilde{\eta}_{yyyy} \right) \end{aligned} \quad (12)$$

## Linear stability analysis

Decomposed into normal modes of the form,

$$\left[ \tilde{w}, \tilde{n}, \tilde{c}, \tilde{\eta} \right] = \left[ W(z), N(z), C(z), \eta \right] e^{i(k_x x + k_y y) + \omega t}. \quad (13)$$

The system of equations become

$$\left[ \frac{d^2}{dz^2} - \left( \frac{\varepsilon \omega}{Pr_\tau} + \varepsilon^2 k^2 \right) \right] \left( \frac{d^2}{dz^2} - \varepsilon^2 k^2 \right) W = -\varepsilon k^2 Ra_\tau N \quad (14a)$$

$$\frac{d^2 N}{dz^2} - S_\tau \frac{dc}{dz} \frac{dN}{dz} - \left( \varepsilon^2 k^2 + \varepsilon \omega + S_\tau \frac{d^2 c}{dz^2} \right) N = \varepsilon \frac{dn}{dz} W$$

$$+ S_\tau \left( n(z) \frac{d^2 C}{dz^2} + \frac{dn}{dz} \frac{dC}{dz} - \varepsilon^2 k^2 n(z) C \right), \quad (14b)$$

$$\frac{d^2 C}{dz^2} - \left( \frac{\varepsilon \omega}{Le_\tau} + \varepsilon^2 k^2 \right) C - \frac{H_\tau}{Le_\tau} N = \frac{\varepsilon}{Le_\tau} \frac{dc}{dz} W, \quad (14c)$$

## Linear stability analysis

The boundary conditions prescribed at the interface  $z = 1$

$$\frac{d^4 W(1)}{dz^4} - \left( \frac{\varepsilon \omega}{Pr_\tau} + 3\varepsilon^2 k^2 \right) \frac{d^2 W(1)}{dz^2} = 0, \quad (15a)$$

$$\frac{d^3 W(1)}{dz^3} + \varepsilon^2 k^2 \frac{dW(1)}{dz} = 0, \quad (15b)$$

$$\begin{aligned} \frac{dN(1)}{dz} - S_\tau \frac{dc(1)}{dz} N(1) - S_\tau n \frac{dC(1)}{dz} &= \frac{S_\tau}{\omega} \frac{dc(1)}{dz} \frac{dn(1)}{dz} W(1) \\ &+ \frac{S_\tau}{\omega} \left( n \frac{d^2 c(1)}{dz^2} - \frac{1}{S_\tau} \frac{d^2 n(1)}{dz^2} \right) W(1), \end{aligned} \quad (15c)$$

$$\omega C(1) + \frac{dc(1)}{dz} W(1) = 0, \quad (15d)$$

## Linear stability analysis

And, at the other boundaries  $z = 0$ , we prescribed

$$W(0) = 0, \quad \frac{dW(0)}{dz} = 0, \quad \frac{dN(0)}{dz} = 0, \quad \frac{dC(0)}{dz} = 0. \quad (16)$$

where  $k = \sqrt{k_x^2 + k_y^2}$ ,  $k_x$  and  $k_y$  are the wave numbers of the disturbance in the  $x$ - and  $y$ -directions, and  $\omega$  is complex.



## Linear stability analysis

Consider possible assumptions with the leading terms which gives non-trivial solutions.

Case I: cell conservation equation is purely diffusive, and oxygen conservation balances between diffusion and consumption of oxygen.

$$Ra_\tau \sim O(1), \quad \omega \sim O\left(\frac{S_\tau H_\tau}{Le_\tau}\right), \quad D^2 C = 0, \quad D^2 N = 0,$$

and, Case II: cell conservation equation is the same, but in oxygen conservation, advection is important as well as the other terms.

$$Ra_\tau \sim O\left(\frac{Le_\tau}{S_\tau H_\tau}\right), \quad \omega \sim O\left(\frac{S_\tau H_\tau}{Le_\tau}\right), \quad D^2 C = N, \quad D^2 N = 0.$$

## Linear stability analysis

Expansions of the form

$$\begin{aligned}
 W(z) &= \sum_{i=0}^{\infty} W_i(z) \left( \frac{S_\tau H_\tau}{Le_\tau} \right)^i, & N(z) &= \sum_{i=0}^{\infty} N_i(z) \left( \frac{S_\tau H_\tau}{Le_\tau} \right)^i, \\
 C(z) &= \sum_{i=0}^{\infty} C_i(z) \left( \frac{S_\tau H_\tau}{Le_\tau} \right)^i, & \omega(k) &= \sum_{i=1}^{\infty} \omega_i(k) \left( \frac{S_\tau H_\tau}{Le_\tau} \right)^i, \\
 \text{and, } Ra_\tau(k) &= \sum_{i=-1}^{\infty} Ra_{\tau i}(k) \left( \frac{S_\tau H_\tau}{Le_\tau} \right)^i. & & (17)
 \end{aligned}$$

So, the governing equations become

$$\frac{d^4 W_0}{dz^4} = -\varepsilon k^2 N_0 Ra_{\tau-1}, \quad \frac{d^2 C_0}{dz^2} = N_0, \quad \frac{d^2 N_0}{dz^2} = 0, \quad (18)$$

## Linear stability analysis

With the boundary conditions

$$\begin{aligned} \frac{d^3 W_0(1)}{dz^3} = 0, \quad \frac{d^2 W_0(1)}{dz^2} = 0, \quad C_0(1) = 0, \quad \frac{dN_0(1)}{dz} = 0, \\ \frac{dW_0(0)}{dz} = 0, \quad W_0(0) = 0, \quad \frac{dN_0(0)}{dz} = 0, \quad \frac{dC_0(0)}{dz} = 0. \end{aligned} \quad (19)$$

Arbitrarily set  $N_0 = 1$  at  $z = 1$  and the corresponding solutions are

$$W_0(z) = -\frac{k^2 \varepsilon Ra_{\tau-1}}{24} z^2 (z^2 - 4z + 6), \quad (20a)$$

$$C_0(z) = \frac{1}{2} (z^2 - 1), \quad (20b)$$

$$N_0(z) = 1. \quad (20c)$$

## Linear stability analysis

At the next order, the governing equations are

$$\begin{aligned} \frac{d^4 W_1}{dz^4} &= \left( \frac{\varepsilon \omega_1}{Pr\tau} + 2k^2 \varepsilon^2 \right) \frac{d^2 W_0}{dz^2} - k^2 \varepsilon (Ra_{\tau 0} N_0 + Ra_{\tau -1} N_1), \\ \frac{d^2 C_1}{dz^2} &= N_1 + k^2 \varepsilon^2 C_0, \\ \frac{d^2 N_1}{dz^2} &= (2 + \varepsilon \omega_1 + k^2 \varepsilon^2) N_0 + z \frac{dN_0}{dz} + z \varepsilon W_0, \end{aligned} \quad (21)$$

with the boundary conditions

$$\begin{aligned} \frac{d^3 W_1(1)}{dz^3} + k^2 \varepsilon^2 \frac{dW_0(1)}{dz} = 0, \quad \frac{d^2 W_1(1)}{dz^2} - (3k^2 \varepsilon^2 + \varepsilon \omega_1) W_0(1) = 0, \\ \omega_1 \frac{dN_1(1)}{dz} - \omega_1 \frac{dC_0(1)}{dz} + \omega_2 \frac{dN_0(1)}{dz} - \omega_1 N_0(1) = 0, \\ C_1(1) = 0, \quad \frac{dW_1(0)}{dz} = 0, \quad W_1(0) = 0, \quad \frac{dN_1(0)}{dz} = 0, \quad \frac{dC_1(0)}{dz} = 0. \end{aligned} \quad (22)$$

## Linear stability analysis

From the solution of the problem at the first order gives the functions  $W_1$ ,  $C_1$  and  $N_1$ , and we can obtain  $\omega_1$  as

$$\omega_1 = \varepsilon k^2 \left( \frac{13}{360} Ra_{\tau-1} - 1 \right). \quad (23)$$

At the second order, we have found  $\omega_2$  as follows:

$$\begin{aligned} \omega_2 = & \frac{k^2}{13!360Pr_{\tau}\omega_1} \left[ 6!Ra_{\tau-1}^2 \left( 1325467\varepsilon^2k^2Pr_{\tau} + \varepsilon^4k^4 \left( 1879648Pr_{\tau} - 474045 \right) \right) \right. \\ & + 13\varepsilon^4k^4Ra_{\tau-1}^3 \left( 624226Pr_{\tau} + 474045 \right) - 13!\varepsilon^2k^2Pr_{\tau} \left( 13Ra_{\tau-1} - 5! \right) \\ & - 6!1716Ra_{\tau-1} \left( 15 \left( Pr_{\tau} \left( 2358\varepsilon^4k^4 + 2882\varepsilon^2k^2 + 7560 \right) - 255\varepsilon^4k^4 \right) \right. \\ & \left. \left. - 2366\varepsilon^2k^2Pr_{\tau}Ra_{\tau-1} \right) \right]. \quad (24) \end{aligned}$$

## Linear stability analysis

The system is unstable to small wavenumber disturbances if  $Ra_{\tau-1} > (360/13)$ . The resultant instability indicates that it is non-oscillatory. It would be interesting to study the marginal stability in which  $\omega_r = 0$  and can calculate  $\omega_j$ . Marginal stability ( $\omega = 0$ ) occurs when

$$Ra_{\tau}(k) = \frac{360}{13(S_{\tau}H_{\tau}/Le_{\tau})} + O(1). \quad (25)$$

## Results: Linear stability

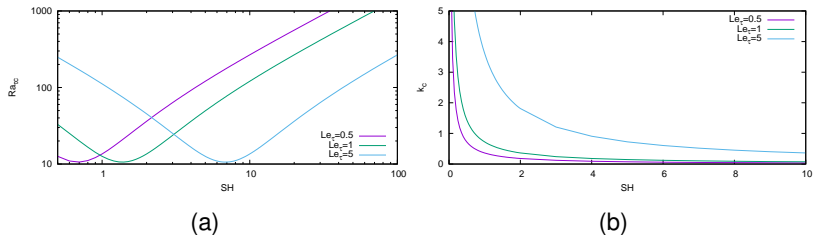


Figure 2: (a)  $Ra_{\tau C}$  and (b) corresponding values of  $k_C$  are computed for the varying values of  $Le_{\tau}$  at  $\varepsilon = 0.1$ . Minimum value of the curve is  $\frac{S_{\tau} H_{\tau}}{Le_{\tau}} \approx 1.036$ .

## Results: Linear stability

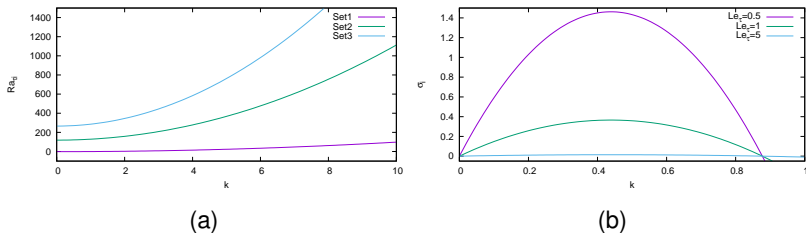


Figure 3: (a)  $Ra_{\tau i}(k)$  curves at the varying sets of parameters, Set 1:  $S_{\tau} = 1$ ,  $H_{\tau} = 1$ ,  $Le_{\tau} = 0.5$ ,  $Pr_{\tau} = 500$ ; Set 2:  $S_{\tau} = 5$ ,  $H_{\tau} = 4$ ,  $Le_{\tau} = 1$ ,  $Pr_{\tau} = 7700$ ; and Set 3:  $S_{\tau} = 10$ ,  $H_{\tau} = 20$ ,  $Le_{\tau} = 5$ ,  $Pr_{\tau} = 500$ ; and (b)  $\omega_i(k)$  curves for varying  $Le_{\tau}$  with fixed value of  $S_{\tau} = 5$ ,  $H_{\tau} = 4$ ,  $\varepsilon = 0.1$ .



## Results: Linear stability

$Le_\tau$	$S_\tau H_\tau$	$Ra_{\tau C}$ -HP	$k_C$ -HP	$Ra_{\tau C}$ -Present	$k_C$ -Present	$\varepsilon$
1	0.05	$1.02 \times 10^4$	1.37	524.738	3.85395	0.1
1	0.05			524.738	1.92697	0.2
1	0.05			524.738	0.77079	0.5
1	1	625	1.58	12.613	0.72176	0.1
1	10	200	1.90	120.596	0.07254	0.1
1	50	328	1.94	709.072	0.01451	0.1
1	100	522	1.91	1447.160	0.00725	0.1
5	10	221	1.24	13.535	0.36268	0.1
5	50	354	1.35	120.596	0.00725	0.1

**Table 1:** Values of  $Ra_{\tau C}$ ,  $k_C$  evaluated for the shallow chamber case. Here, -HP represents the values from Hillesdon and Pedley (1996) for flat free surface and -Present represents the values of the present study for deformed free surface.

## Weakly nonlinear analysis

$$\begin{aligned} \mathbf{u} &= \mathbf{u}_0 + \tilde{\mathbf{u}}, & p &= p_0 + \tilde{p}, & n &= n_0 + \tilde{n}, \\ \text{and} & & c &= c_0 + \tilde{c}, & h &= h_0 + \tilde{h}. \end{aligned} \quad (26)$$

The scales of these perturbations are

$$\frac{\mathbf{u}'}{\mathbf{u}_0} \sim \frac{p'}{p_0} \sim \frac{n'}{n_0} \sim \frac{c'}{c_0} \sim \varepsilon.$$

Express  $\mathbf{u}$ ,  $p$ ,  $n$ ,  $c$ , and  $h$  in terms of  $\varepsilon$  as

$$[\mathbf{u}, n, c, p, h] = \sum_{n=0}^3 \varepsilon^n [\mathbf{u}_n, n_n, c_n, p_n, h_n](x, y, z, t, T) + O(\varepsilon^4) \quad (27a)$$

$$Ra_\tau = Ra_{\tau c} + \varepsilon Ra_{\tau 1} + \dots, \quad (27b)$$

A slow timescale  $T$  is chosen to be  $T = \varepsilon t$ .

## Weakly nonlinear analysis

Obtain the steady-state equations for  $n(z)$  and  $c(z)$  at  $O(1)$ . At  $O(\varepsilon)$ , obtain the linear system of equations where the variables  $w_1$ ,  $n_1$ , and  $c_1$  are expressed as

$$\begin{aligned}w_1 &= W(z)\Re(A_1(T)e^{iky} + A_2(T)e^{-\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky} + A_3(T)e^{\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky}), \\n_1 &= N(z)\Re(A_1(T)e^{iky} + A_2(T)e^{-\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky} + A_3(T)e^{\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky}), \\c_1 &= C(z)\Re(A_1(T)e^{iky} + A_2(T)e^{-\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky} + A_3(T)e^{\frac{\sqrt{3}}{2}ikx - \frac{1}{2}iky}),\end{aligned}$$

where the amplitudes  $A_i (i = 1, 2, 3)$  for rolls become  $A_1 = A$ ,  $A_2 = A_3 = 0$  and for hexagons  $A_1 = A_2 = A_3 = A$ .

## Weakly nonlinear analysis

At  $O(\varepsilon^2)$ , the equations give rise to the solvability condition as follows:

$$\int \mathbf{v} \cdot \mathbf{RHS} dx + \int \int \left( v_2 n_1 \frac{\partial c_1}{\partial y} \right) \Big|_{z=0} dx dy = 0, \quad (29)$$

where the first-order adjoint  $\mathbf{v} = (v_1, v_2, v_3)$  denotes the variables  $(w_1, n_1, c_1)$ .

Three solvability conditions can be obtained by setting

$\mathbf{v} = V(z) \bar{A}_1 e^{-iky}$ ,  $\mathbf{v} = V(z) \bar{A}_2(T) e^{\frac{\sqrt{3}}{2} ikx + \frac{1}{2} iky}$ , and

$\mathbf{v} = V(z) \bar{A}_3 e^{-\frac{\sqrt{3}}{2} ikx + \frac{1}{2} iky}$  and substituting the nine expressions into (29) and then performing integration to obtain

$$\xi_1 \frac{dA_1}{dT} + Ra_{\tau 1} \xi_3 + \xi_2 \bar{A}_2 \bar{A}_3 = 0. \quad (30)$$

## Weakly nonlinear analysis

For steady rolls where  $A_1 = A$ ,  $A_2 = A_3 = 0$  and  $dA/dT = 0$ , the existing solvability conditions imply that  $Ra_{\tau 1} = 0$ . For steady hexagons where  $A_1 = A_2 = A_3 = A$  and  $dA/dT = 0$ ,

$$Ra_{\tau 1} = -\frac{\xi_2}{\xi_3} A. \quad (31)$$

A stability analysis of (30) exhibits that the branches of roll bifurcation are unstable.

Redefine  $Ra_{\tau} = Ra_{\tau c} + \varepsilon^2 Ra_{\tau 2}$  and consider  $T = \varepsilon^2 t$ .

## Conclusions

- ▶ Parametric study:  $S_\tau$ ,  $H_\tau$  and  $Le_\tau$  are independently varied to determine  $Ra_\tau$  and  $k$ .
- ▶ The instability generates as the values of  $S_\tau$ ,  $H_\tau$  and  $Le_\tau$  increase, although this effect is reversed as the length of the chamber increases.
- ▶ The wave number increases with the length of the chamber as well as the peak of temporal growth.

Weakly nonlinear analysis and bifurcation study is in progress.

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# Stability analysis of a three-dimensional chemotaxis system

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## Thank you