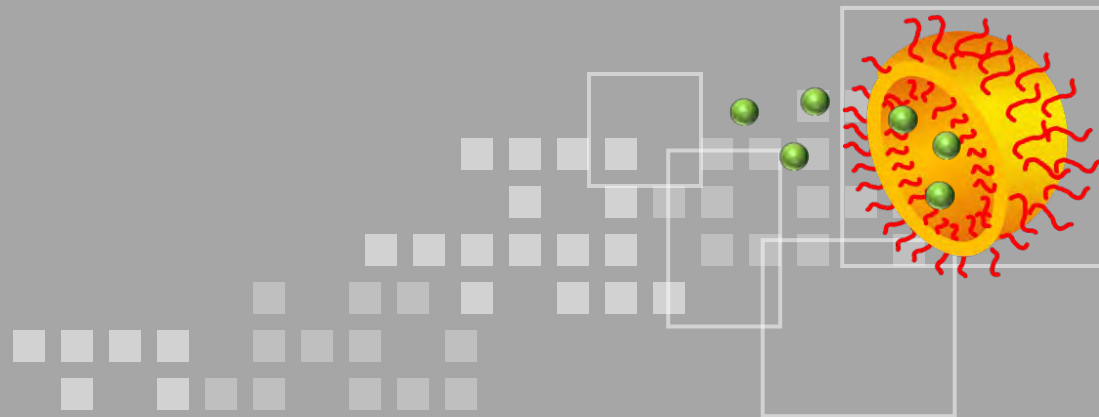




National Taiwan University
Department of Chemical Engineering

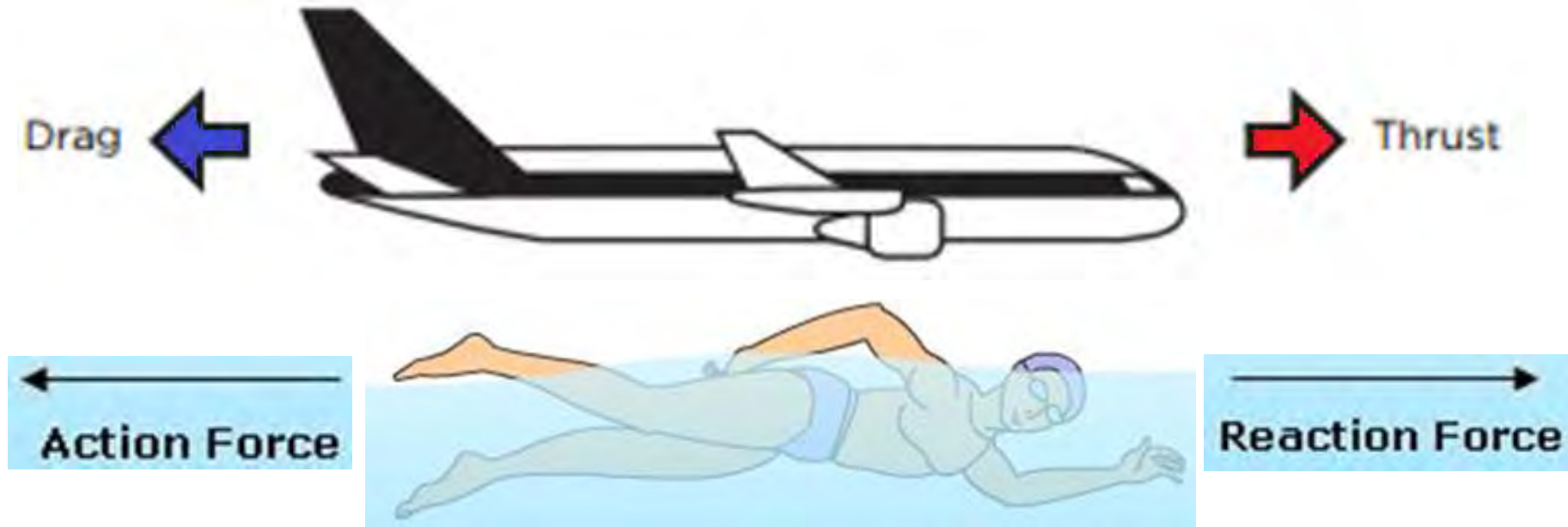
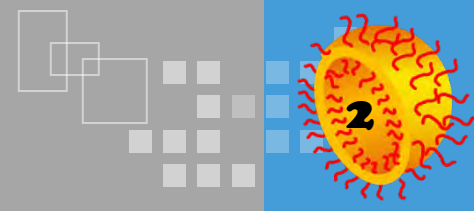


Rectification of a Nano/Micro-Swimmer System : A Dissipative Particle Dynamics Study

Yu-Jane Sheng



Introduction : Propulsion / Swimmer

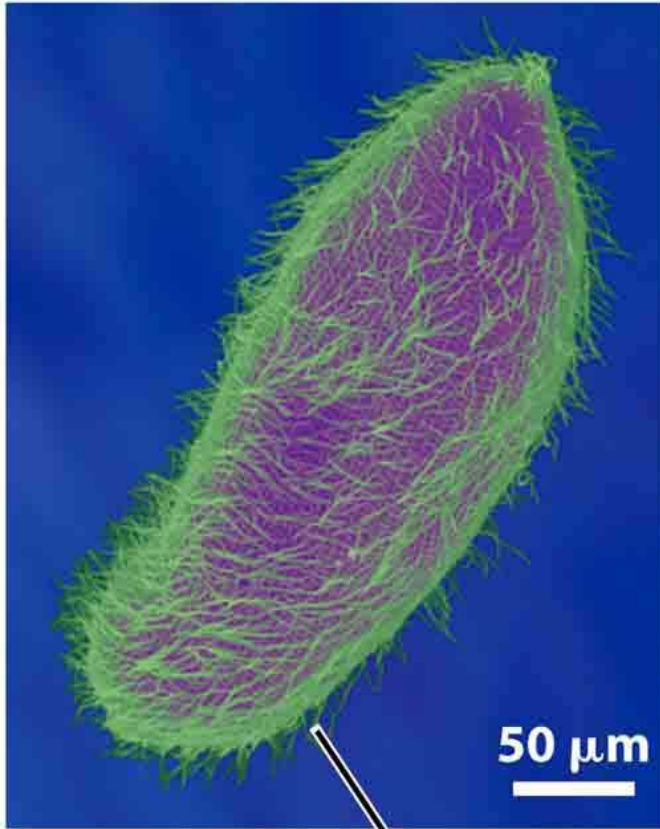
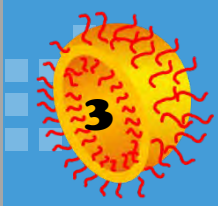
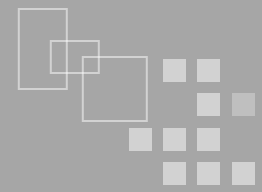


(Swimmer pushes water
in the backward direction)

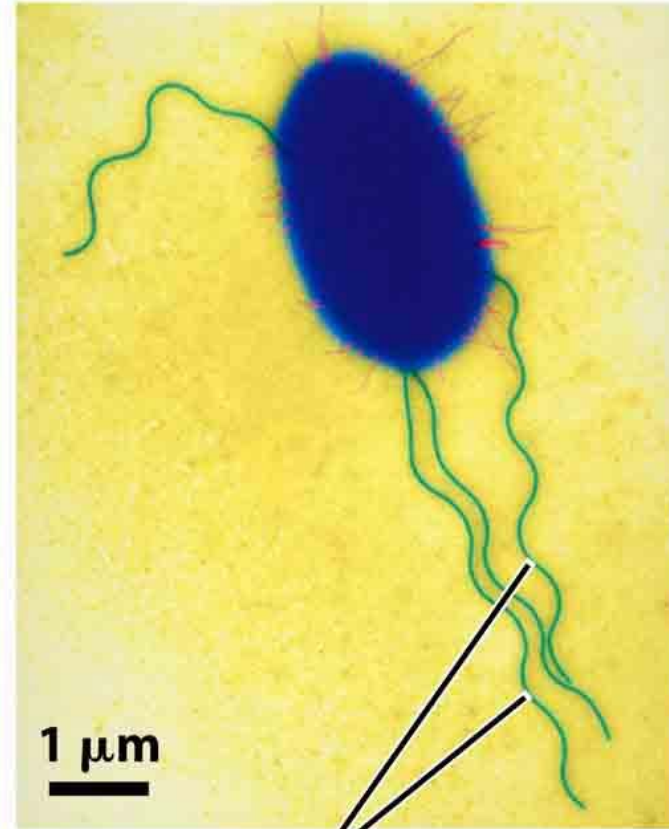
(Water exerts a force
on the swimmer)

Self-propelled swimmers **consume energy** from internal or external sources and dissipate it by **actively moving** through the medium that they inhabit.

Microswimmer



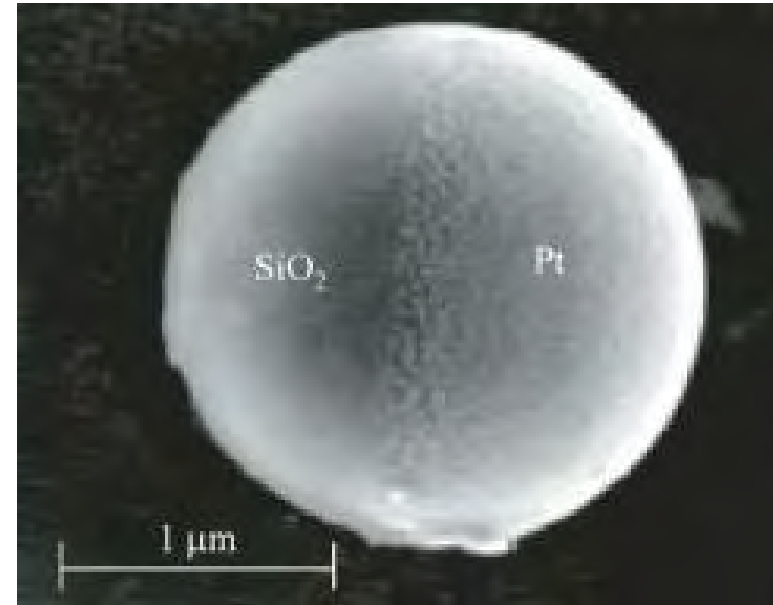
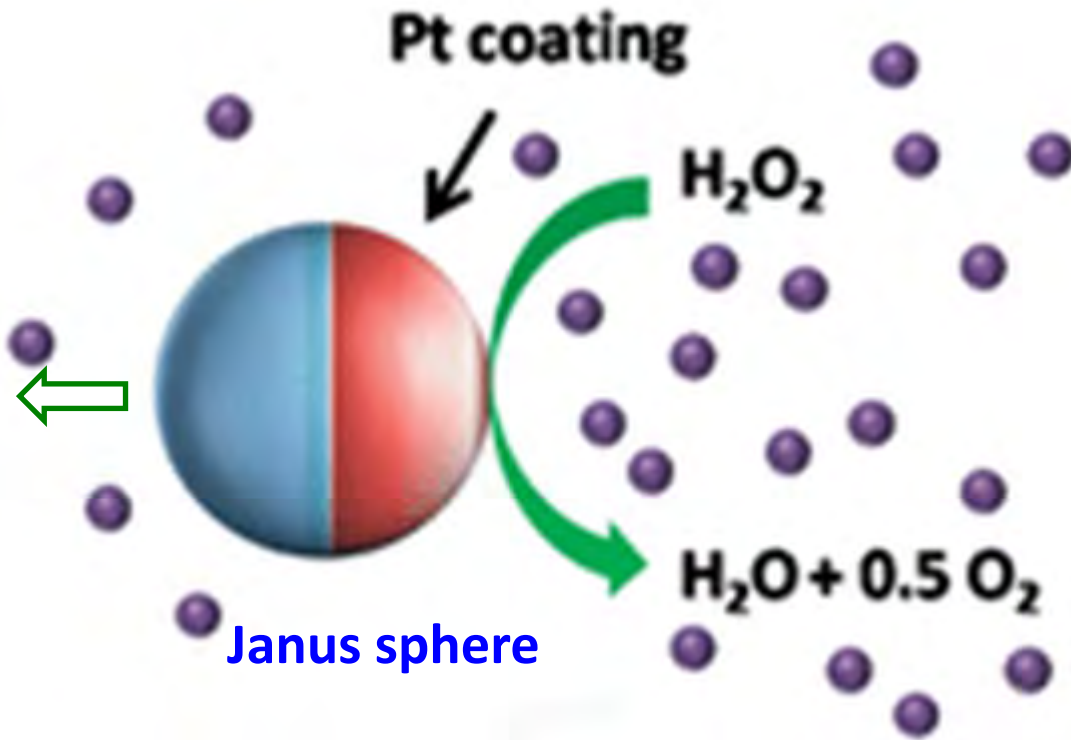
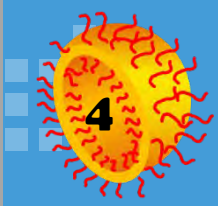
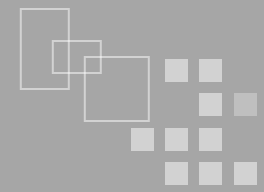
Cilia



Flagella

Microorganisms utilize a wide variety of swimming mechanisms such as beating cilia and flagellar propulsion to propel themselves.

Artificial Swimmer

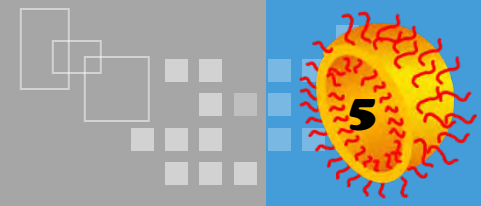


Janus sphere

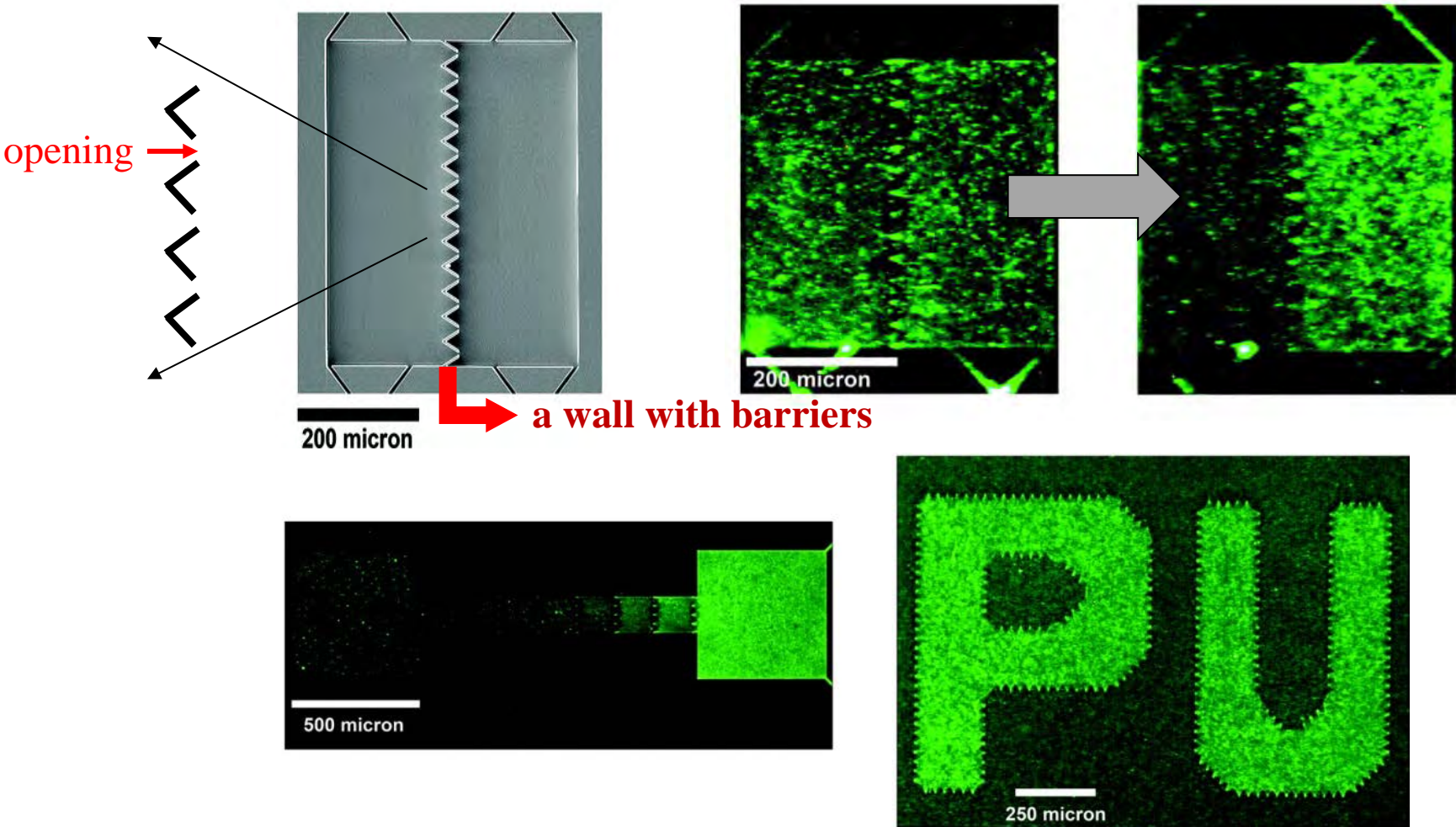
chemical energy \rightarrow kinetic energy

Self-propulsion of a Janus sphere via the **asymmetric distribution of reaction products** and an accompanying osmotic potential.

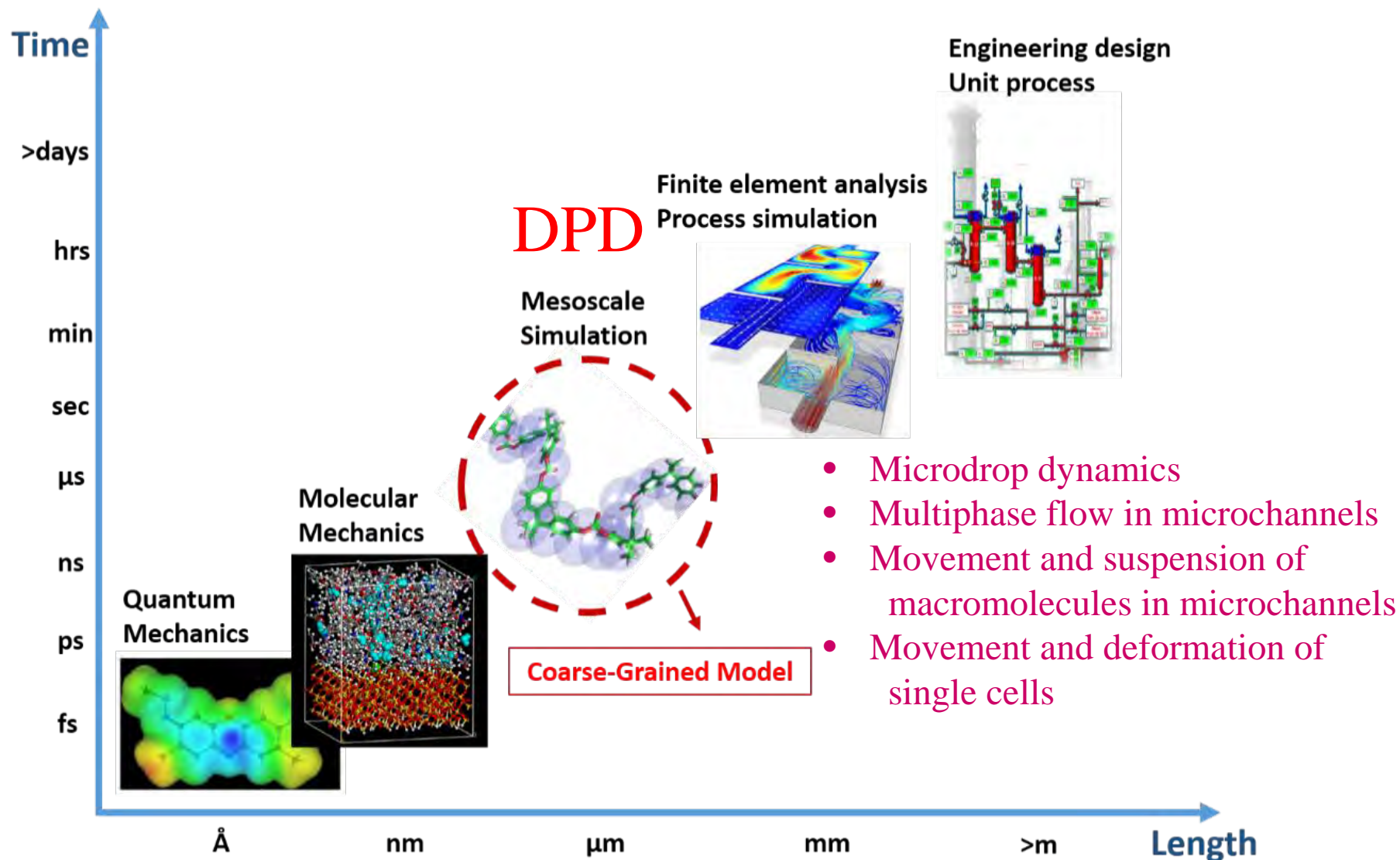
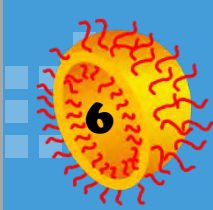
Rectification Phenomenon



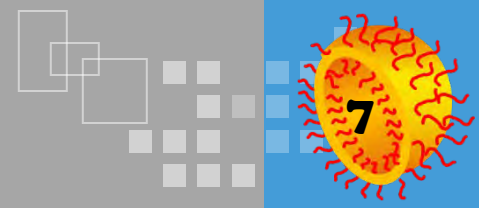
The concentration difference of E. coli occurs through barrier walls.



Simulation Method : Dissipative Particle Dynamics (DPD)

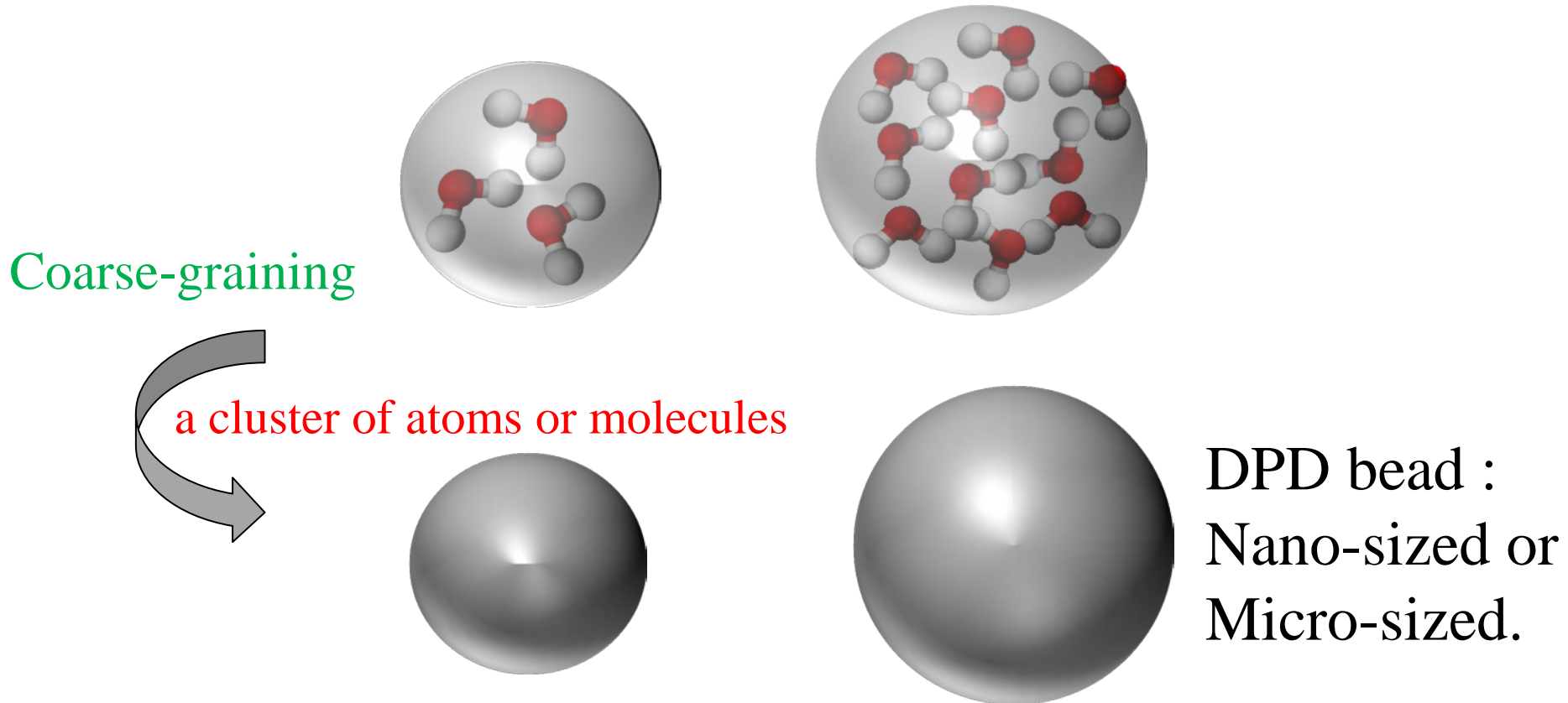


Coarse-Graining of Small Molecules

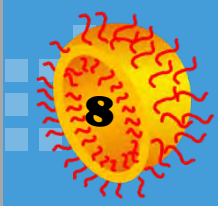
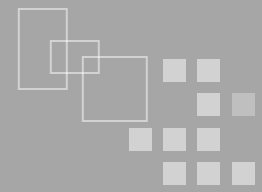


DPD is an off-lattice and particle-based simulation method.

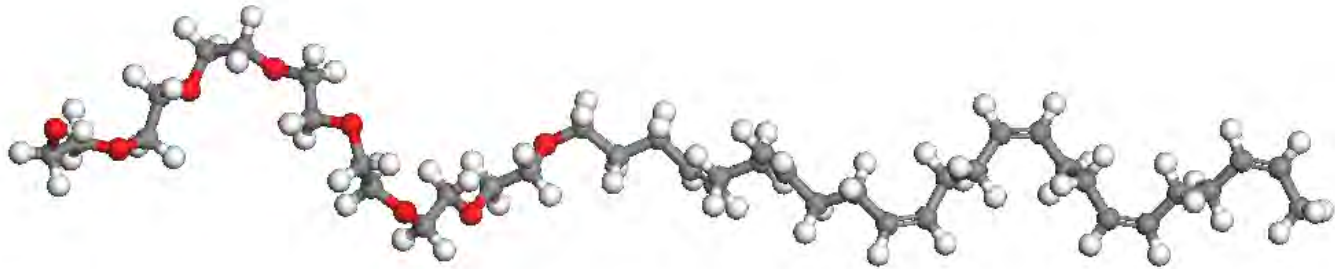
- Some trivial molecular details that do not affect the behavior at larger scales can be ignored, while the main features of concerned physics need to be effectively obtained.



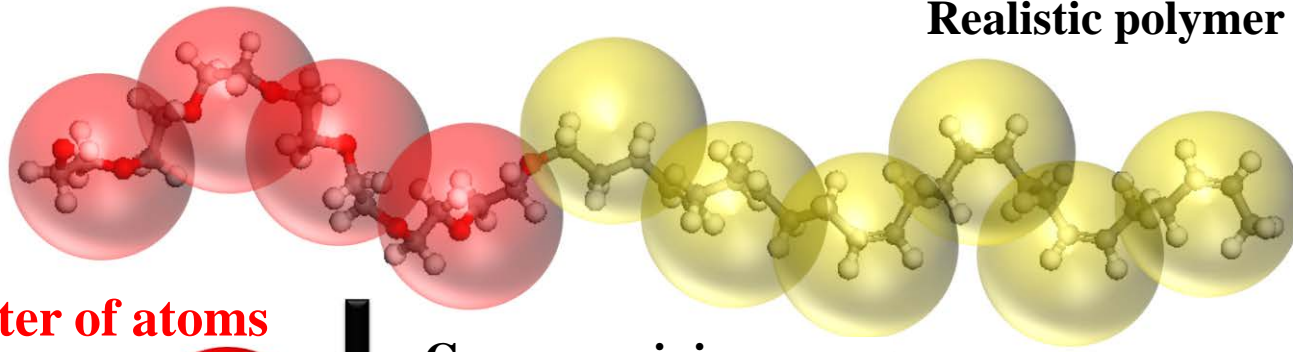
Coarse-Graining of a Polymer



poly(ethylene oxide)-block-polybutadiene diblock copolymer (PEO-b-PB)



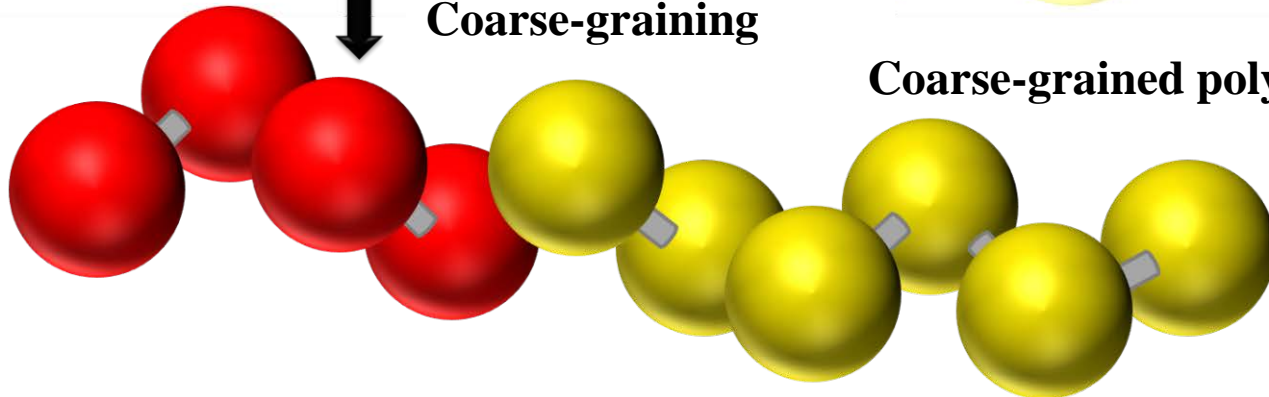
Realistic polymer



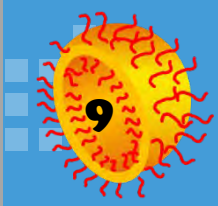
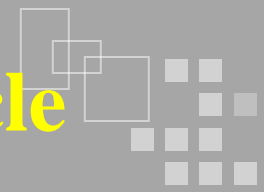
a cluster of atoms

Coarse-graining

Coarse-grained polymer

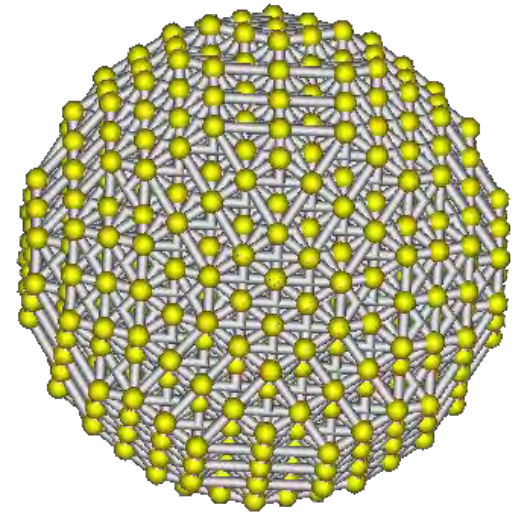


Coarse-Graining of a Colloidal Particle

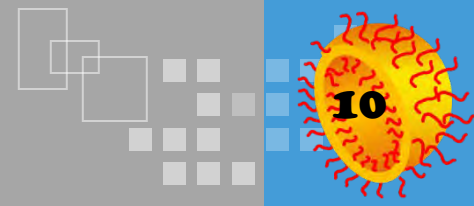


Colloidal Silica

Coarse-graining



DPD Microswimmer



Time evolution

■ Newton's law of motion

$$\frac{d\mathbf{r}_i}{dt} = \mathbf{v}_i; \quad \frac{d\mathbf{v}_i}{dt} = \frac{\mathbf{f}_i}{m_i}$$

■ Non-bonded DPD forces

$$\mathbf{f}_i = \sum_{j \neq i} (\mathbf{F}_{ij}^C + \mathbf{F}_{ij}^D + \mathbf{F}_{ij}^R)$$

1. Conservative force (\mathbf{F}_{ij}^C)

2. Dissipative force (\mathbf{F}_{ij}^D)

3. Random force (\mathbf{F}_{ij}^R)

Conservative Force

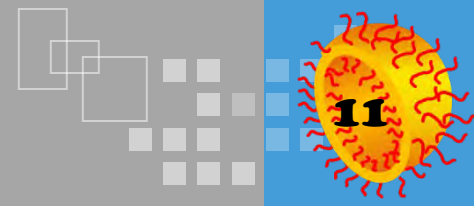
$$\mathbf{F}_{ij}^C = \begin{cases} a_{ij} (r_c - r_{ij}) \hat{\mathbf{r}}_{ij}, & r_{ij} < r_c \\ 0, & r_{ij} \geq r_c \end{cases}$$

Interaction parameter

Cutoff radius

- ✓ Soft repulsive force
- ✓ a_{ij} is a maximum repulsion between particles i and j .
- ✓ The conservative force provide beads a chemical identity.

DPD : Dissipative Force



Mesoscale simulation

■ Newton's law of motion

$$\frac{d\mathbf{r}_i}{dt} = \mathbf{v}_i; \quad \frac{d\mathbf{v}_i}{dt} = \frac{\mathbf{f}_i}{m_i}$$

■ Non-bonded DPD forces

$$\mathbf{f}_i = \sum_{j \neq i} (\mathbf{F}_{ij}^C + \mathbf{F}_{ij}^D + \mathbf{F}_{ij}^R)$$

1. Conservative force (\mathbf{F}_{ij}^C)

2. Dissipative force (\mathbf{F}_{ij}^D)

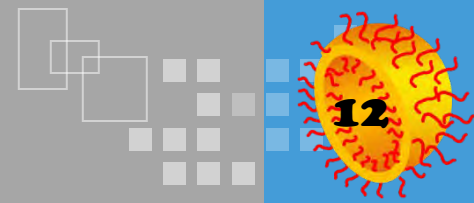
3. Random force (\mathbf{F}_{ij}^R)

Dissipative Force

$$\mathbf{F}_{ij}^D = -\underbrace{\gamma}_{\text{Friction coefficient}} \underbrace{\omega^D}_{\text{r-dependent weight function}} (\hat{\mathbf{r}}_{ij} \cdot \mathbf{v}_{ij}) \hat{\mathbf{r}}_{ij}$$

- ✓ Frictional force
- ✓ Represents viscous resistance within the fluid
- ✓ Reduce the relative velocity of the pair of beads. (leading to energy loss)

$$\omega^D(r) = \left(1 - \frac{r_{ij}}{r_c}\right)^2, \quad r_{ij} < r_c$$



Mesoscale simulation

■ Newton's law of motion

$$\frac{d\mathbf{r}_i}{dt} = \mathbf{v}_i; \quad \frac{d\mathbf{v}_i}{dt} = \frac{\mathbf{f}_i}{m_i}$$

■ Non-bonded DPD forces

$$\mathbf{f}_i = \sum_{j \neq i} (\mathbf{F}_{ij}^C + \mathbf{F}_{ij}^D + \mathbf{F}_{ij}^R)$$

1. Conservative force (\mathbf{F}_{ij}^C)

2. Dissipative force (\mathbf{F}_{ij}^D)

3. Random force (\mathbf{F}_{ij}^R)

Random Force

$$\sigma = (2\gamma k_B T)^2$$

$$\omega^R = (\omega^D)^{1/2}$$

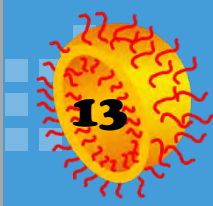
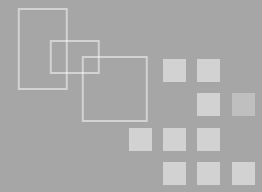
$$\mathbf{F}_{ij}^R = -\overset{\substack{\downarrow \\ \text{Noise amplitude}}}{\sigma} \omega^R \underset{\substack{\downarrow \\ \text{r-dependent} \\ \text{weight function}}}{\xi_{ij}} \hat{\mathbf{r}}_{ij}$$

- ✓ Compensates for lost degrees of freedom eliminated after the coarse-graining.
- ✓ Puts in energy to the system with inducing energy fluctuation.

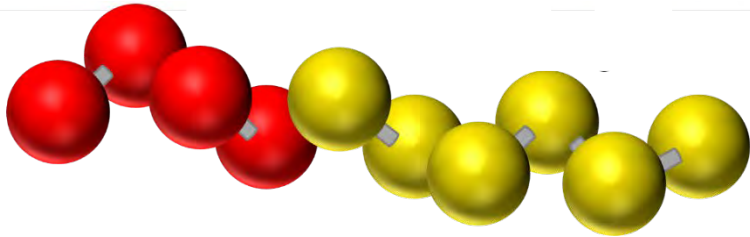
DPD thermostat

- Constant mean temperature of the system
- Correct description of hydrodynamics

P. Espanol and P. Warren, *EPL*, 1995, **30**, 191.



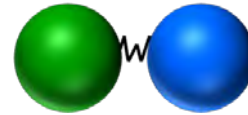
Model Polymer



Connectness:

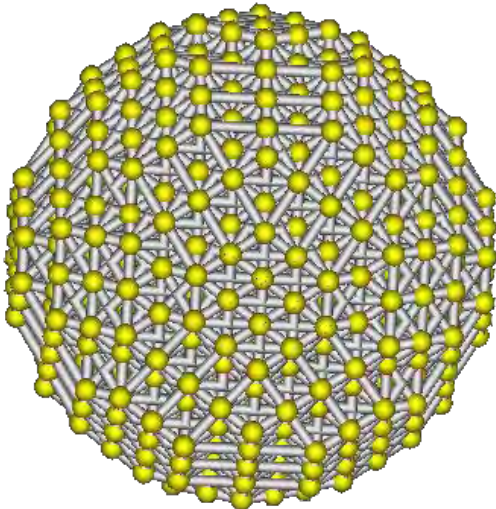
Spring Force

$$F_{ij}^S = -\sum_j C^S (r_{ij} - r_{eq}^S) \hat{r}_{ij}$$



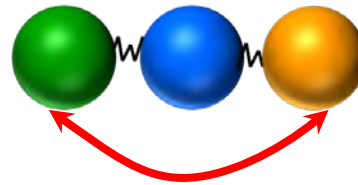
$$C^S = 100 \quad r_{eq}^S = 0.7$$

Model Microswimmer



Rigidity:

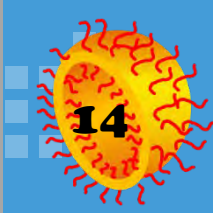
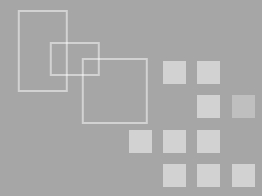
Angle Force



$$F_{ij}^{S\theta} = -\sum_j C^\theta (r_{ij} - r_{eq}^\theta) \hat{r}_{ij}$$

$$C^\theta = 100 \quad r_{eq}^\theta = 2r_{eq}^S = 1.4$$

Modified Velocity-Verlet Algorithm



14

$$\frac{d\mathbf{r}_i}{dt} = \mathbf{v}_i \quad \frac{d\mathbf{v}_i}{dt} = \frac{\mathbf{f}_i}{m_i} \quad \text{Initial position and velocity for each bead are provided.}$$

To advance the set of positions and velocities, a modified version of the velocity-Verlet algorithm is used,

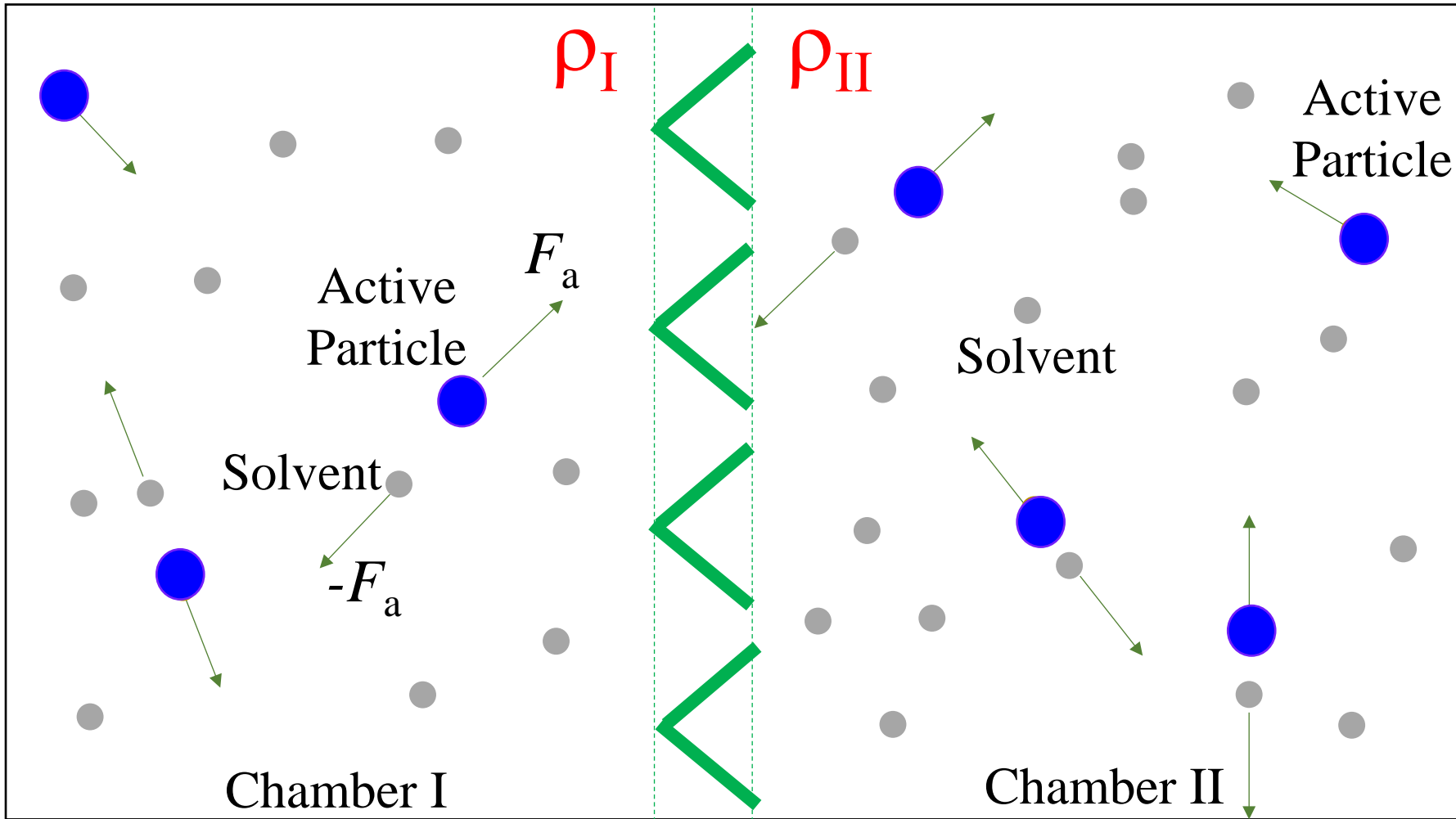
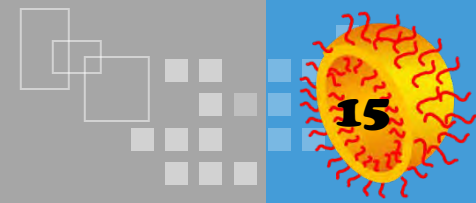
$$\mathbf{r}_i(t + \Delta t) = \mathbf{r}_i(t) + \Delta t \mathbf{v}_i(t) + \frac{1}{2} (\Delta t)^2 \mathbf{f}_i(t),$$

$$\tilde{\mathbf{v}}_i(t + \Delta t) = \mathbf{v}_i(t) + \lambda \Delta t \mathbf{f}_i(t),$$

$$\mathbf{f}_i(t + \Delta t) = \mathbf{f}_i(\mathbf{r}(t + \Delta t), \tilde{\mathbf{v}}(t + \Delta t)),$$

$$\mathbf{v}_i(t + \Delta t) = \mathbf{v}_i(t) + \frac{1}{2} \Delta t (\mathbf{f}_i(t) + \mathbf{f}_i(t + \Delta t)).$$

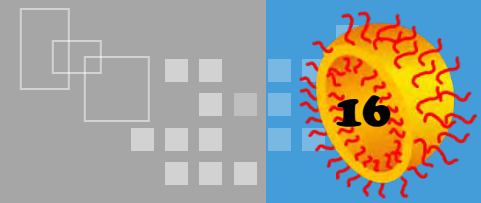
Simulation System



ρ : active particle density

Rectification ratio $A_r (= \rho_{II} / \rho_I)$

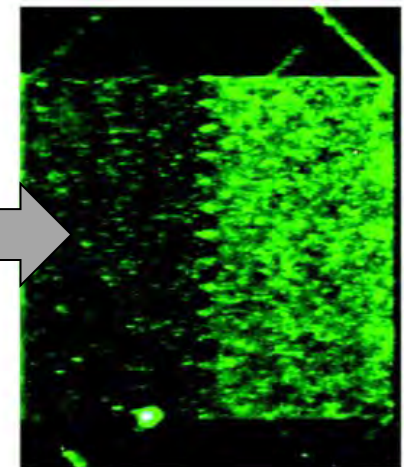
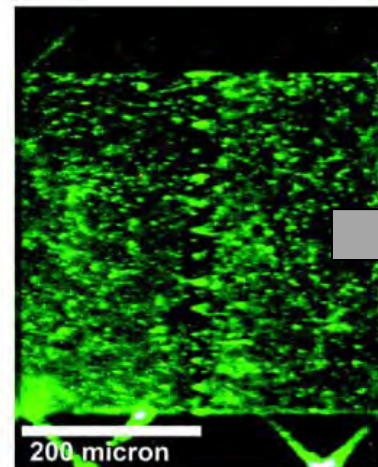
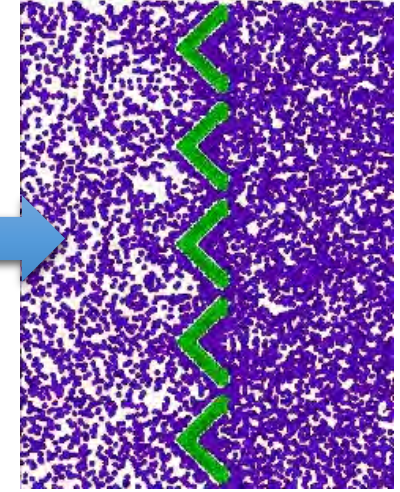
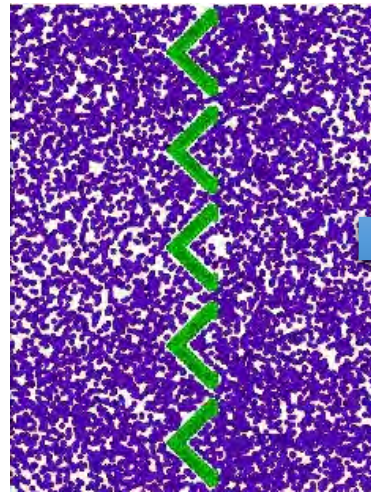
Simulation Movie



$$A_r (= \rho_{II} / \rho_I) = 2.2$$

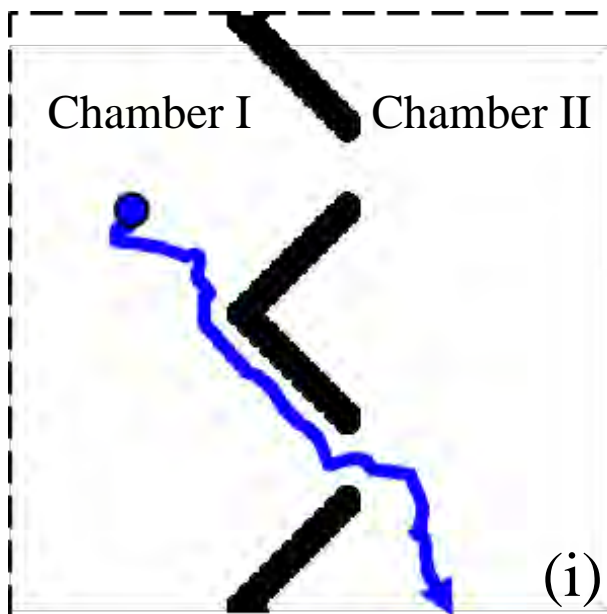
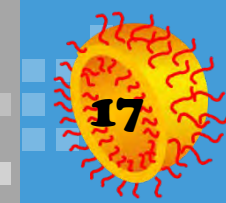
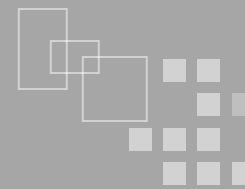
Initial state

Final state

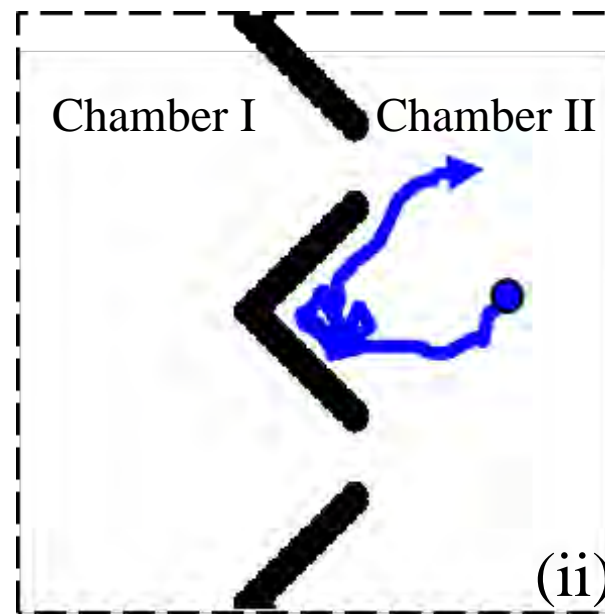


✓ Only the movements of active particles are shown.

Rectification Mechanism



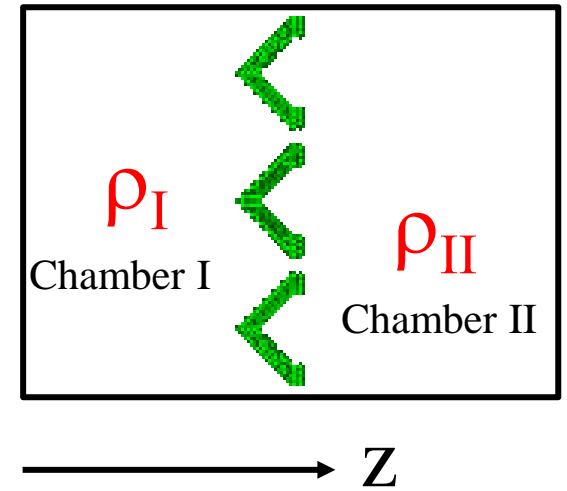
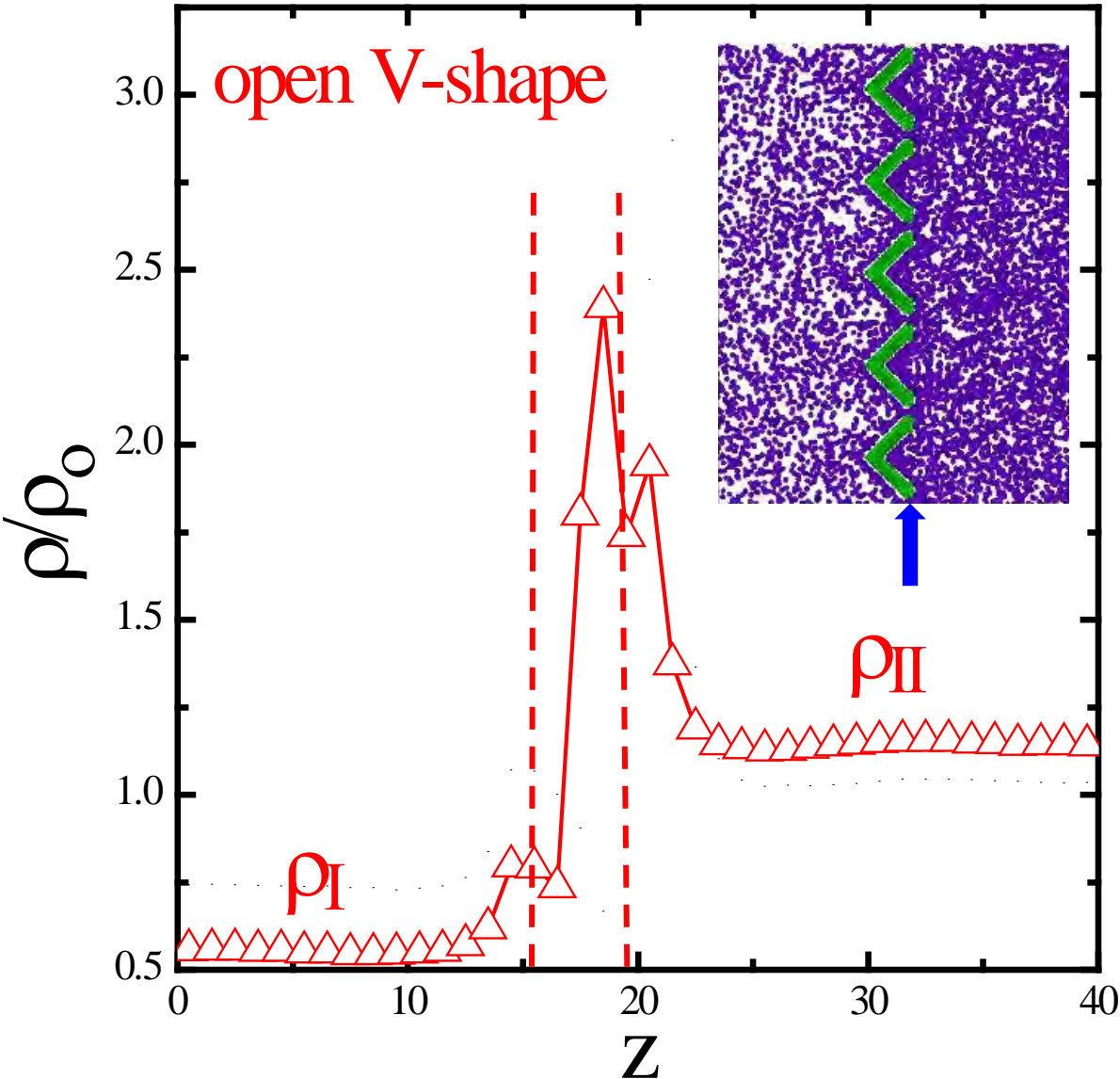
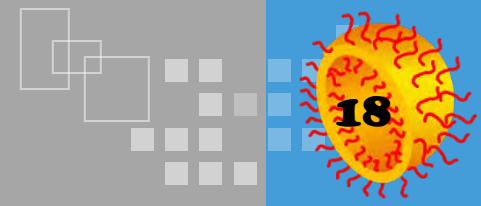
Geometry-assisted
diffusion



Trap-hindered
diffusion

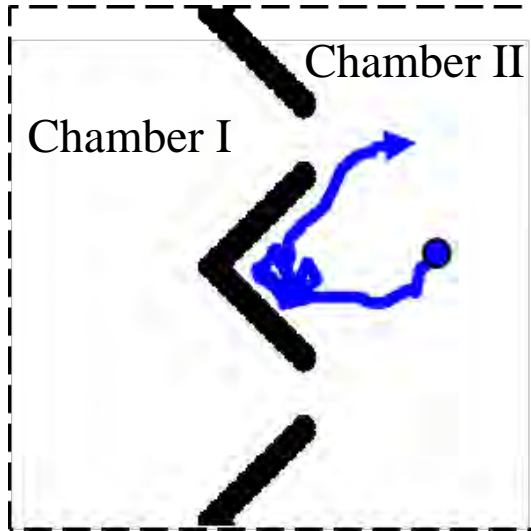
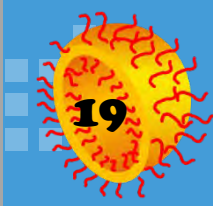
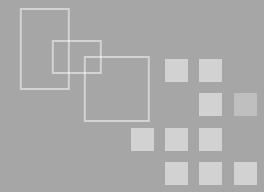
The coupling effect leads to the rectification outcome.

Density Profile

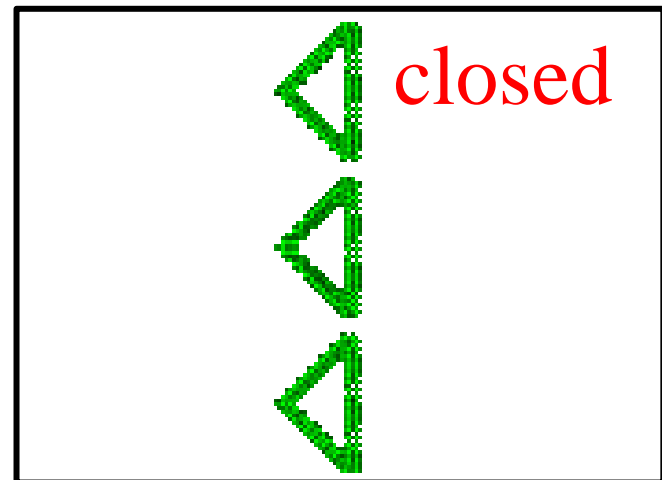
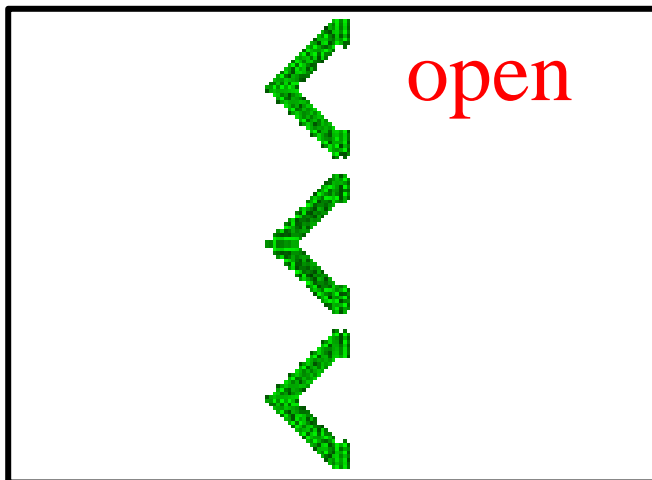
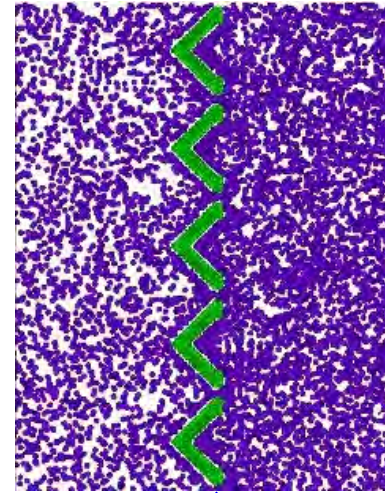


rectification ratio
 $A_r (= \rho_{II} / \rho_I) = 2.2$

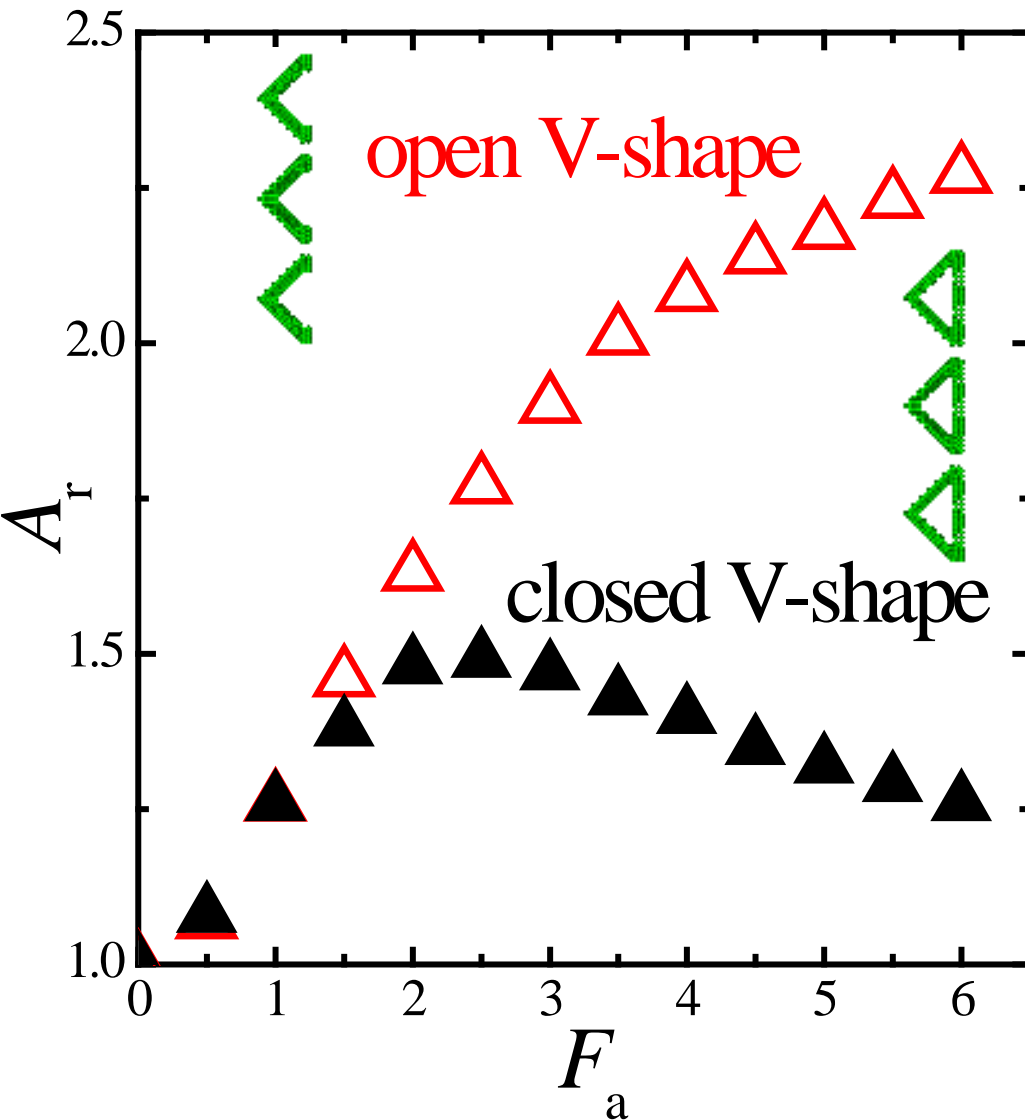
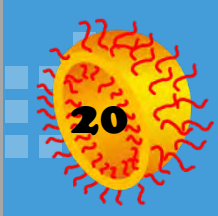
The Effect of the Trap



Trap-hindered effect



The Comparison of Rectification Ratio between Open and Closed V-shape Barriers



Open barriers:

$$F_a \uparrow , A_r \uparrow$$

Closed barriers:

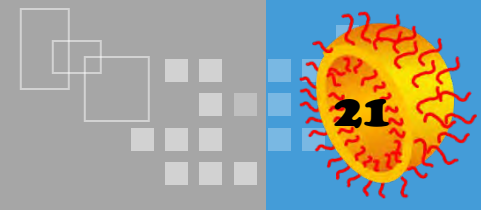
A maximum exists for

$$A_r \text{ vs } F_a$$

Trap-hindered diffusion
is important.

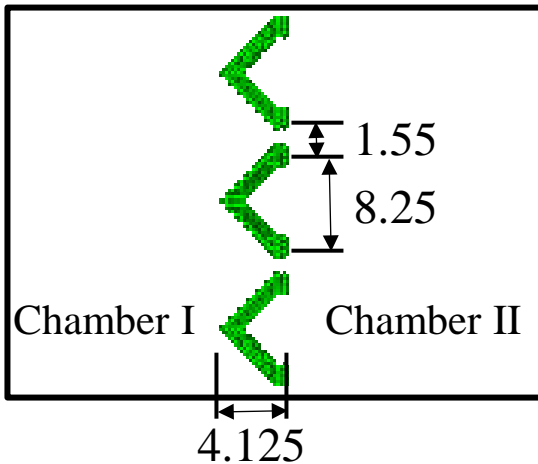
Open barrier > Closed barrier

The Effects of Barrier Structures

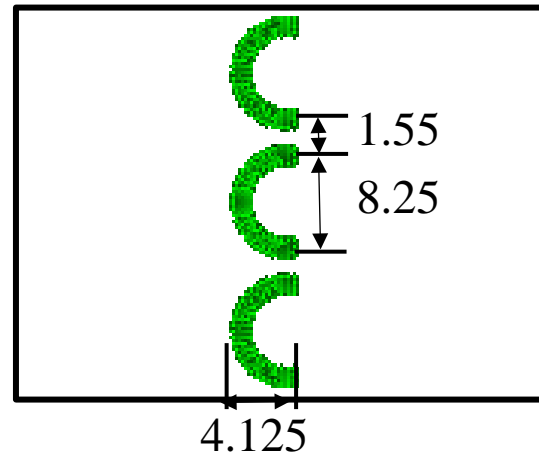


Open barriers

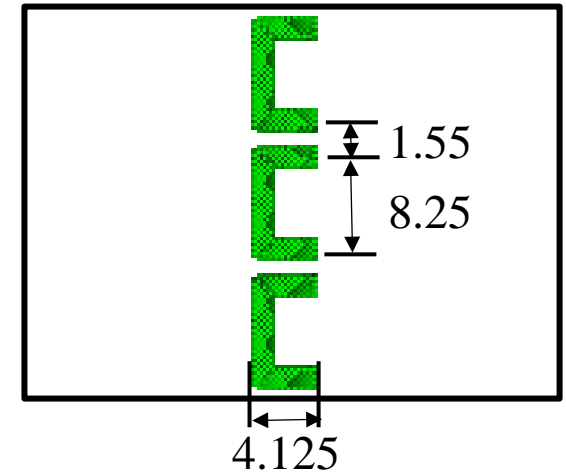
V-shape



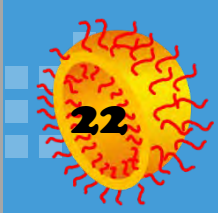
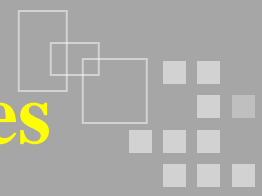
circular



rectangular

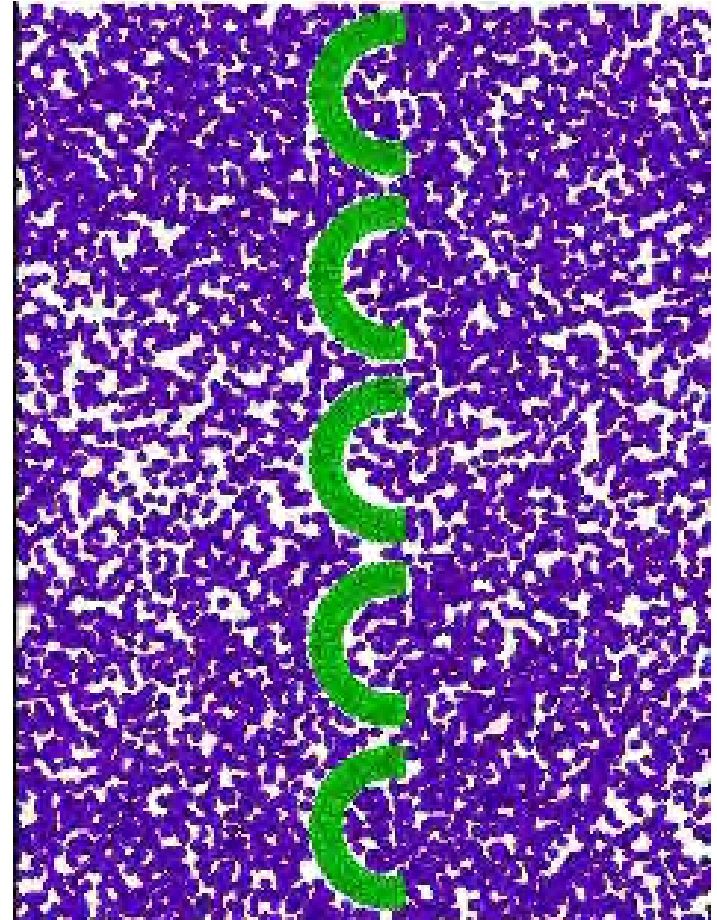
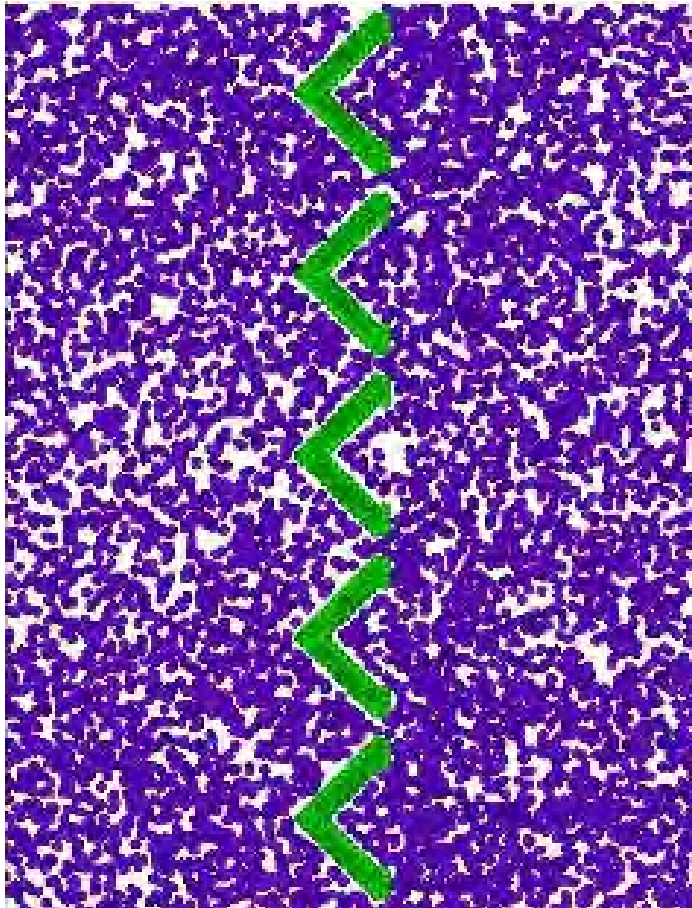


Simulation Movies : Barrier Structures

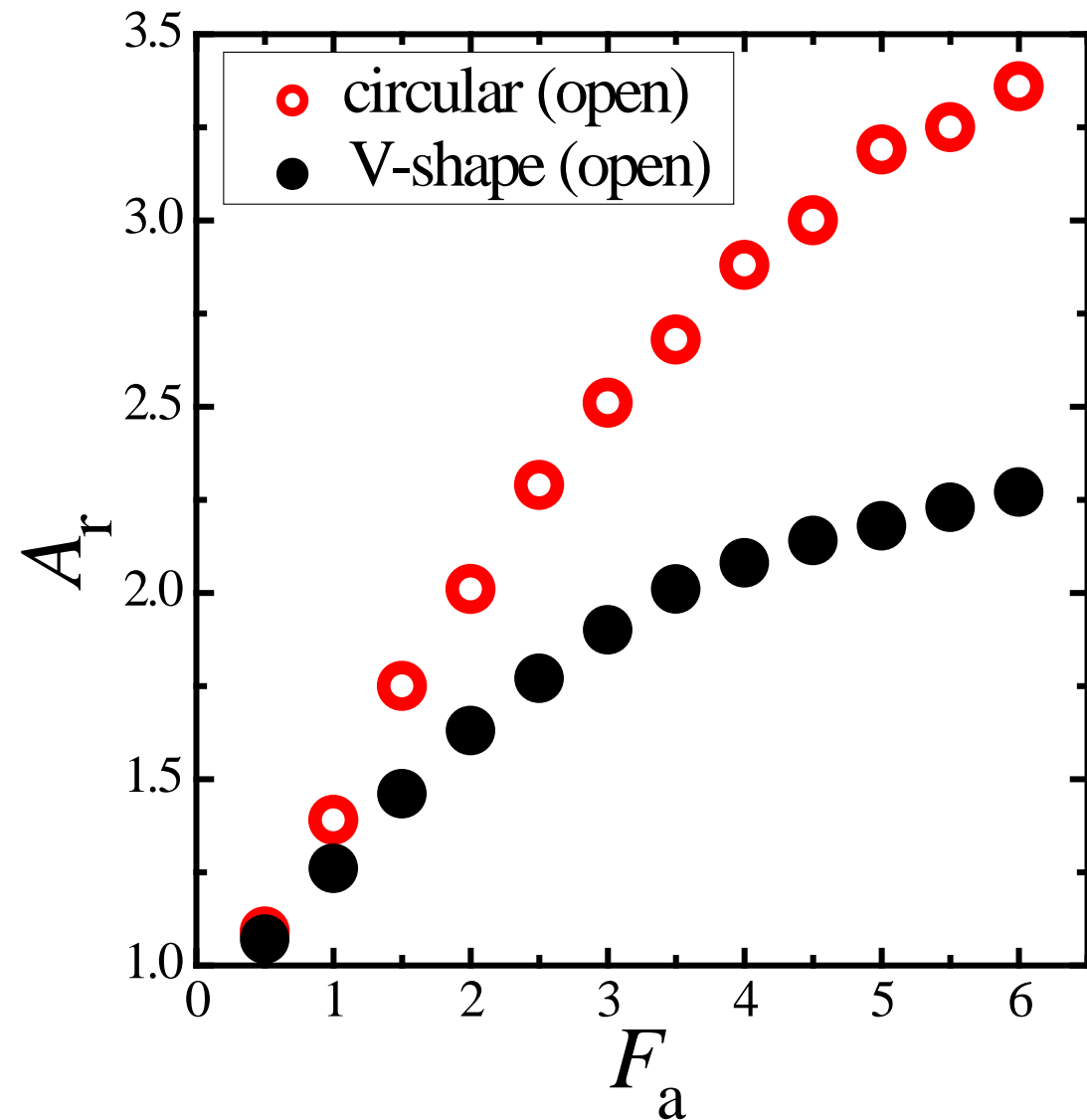


V-shape, $A_r = 2.2$

Circular, $A_r = 3.4$



The Comparison of Rectification Ratio between Different Barrier Structures

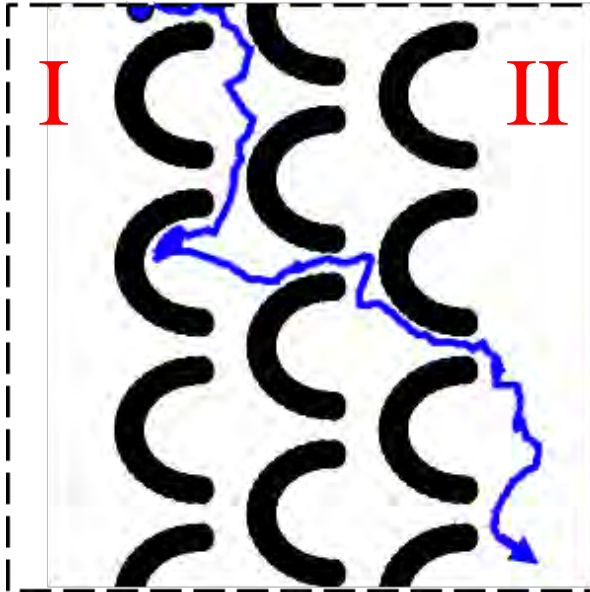
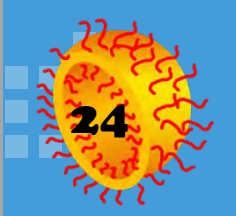
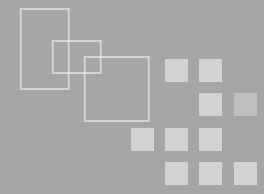


Open barriers:

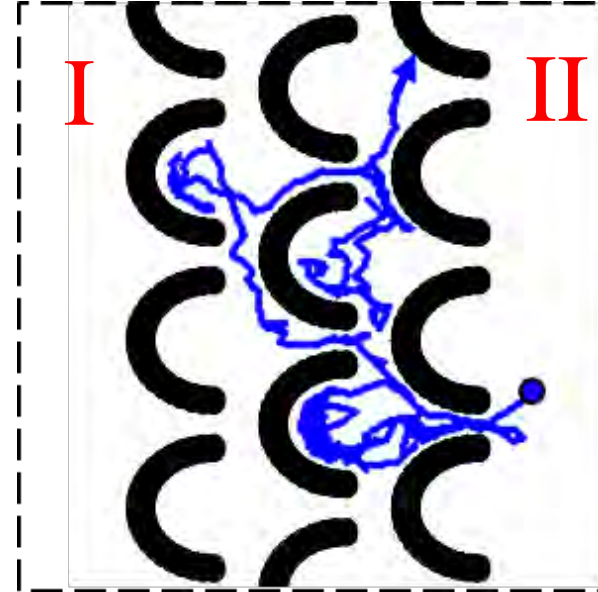
$$F_a \uparrow , A_r \uparrow$$

Circular > Rectangular
> V-shape

Multilayered Enhancement



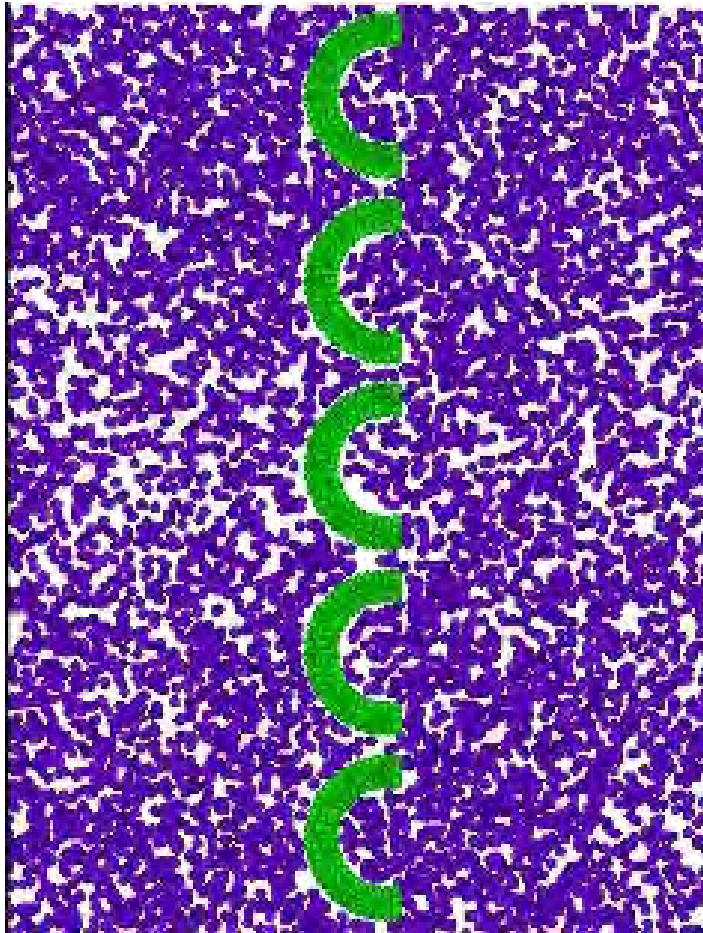
Geometry-assisted
diffusion



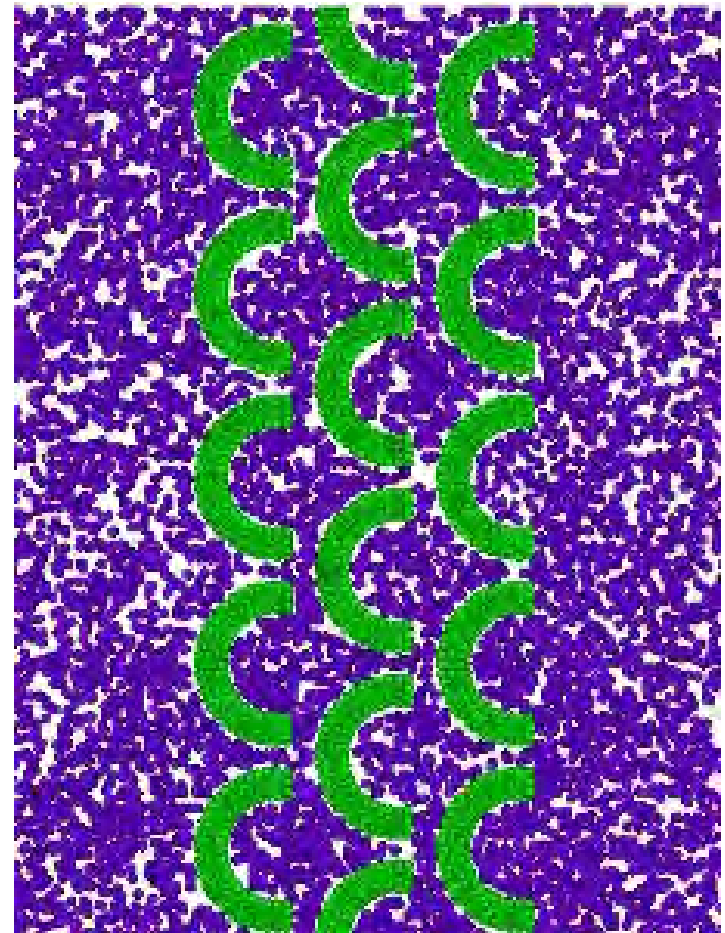
Trap-hindered
diffusion



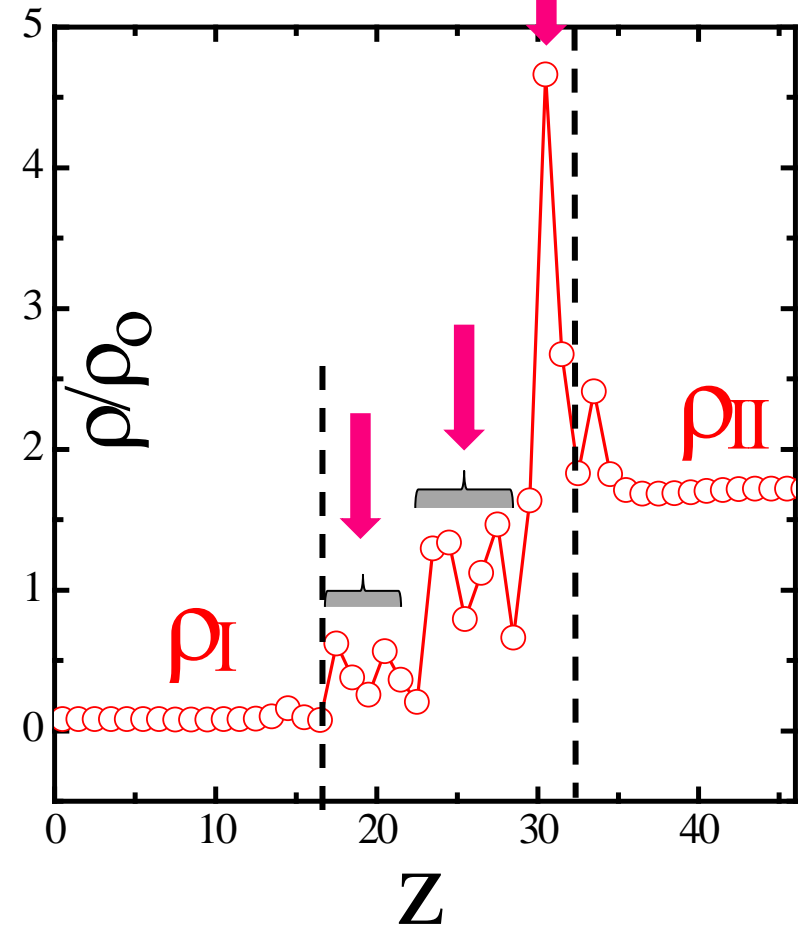
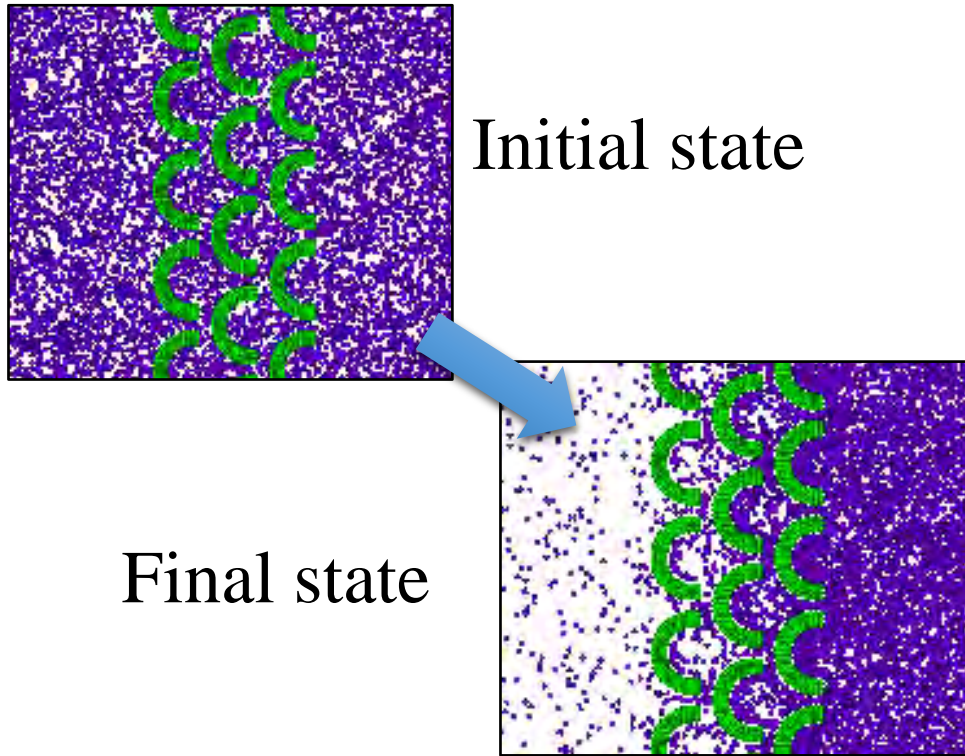
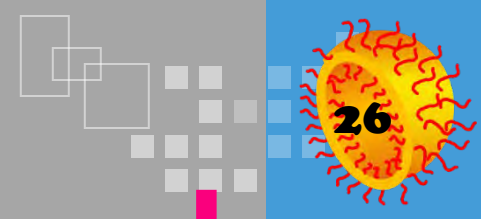
Single, $A_r = 3.4$



Triple, $A_r = 32$

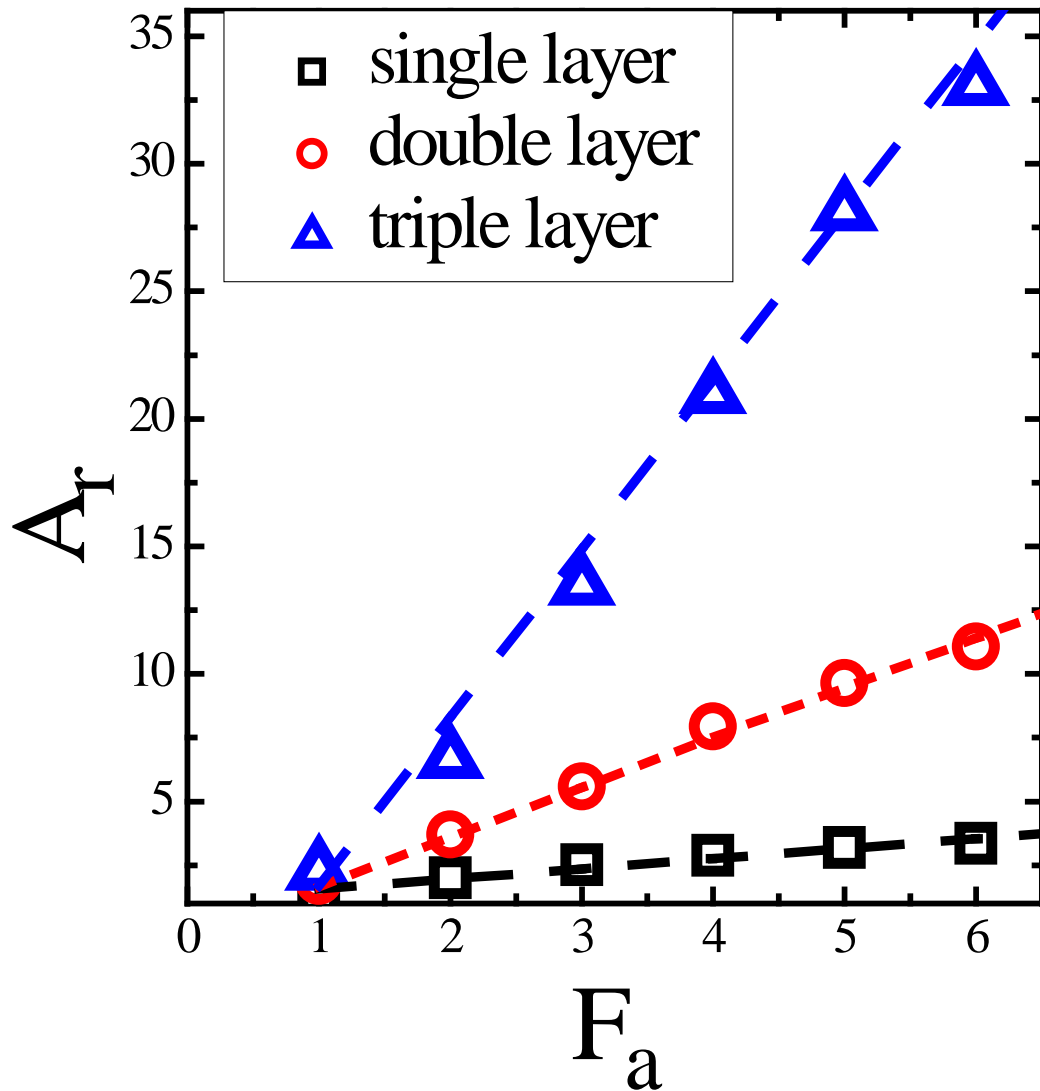


Multilayered Enhancement : Density Profile



Rectification ratio
 $A_r (= \rho_{II} / \rho_I) = 32$

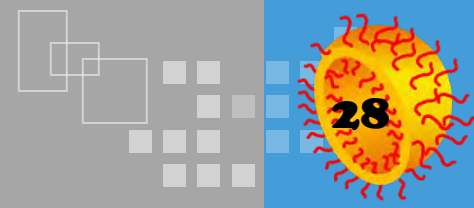
The Comparison of Rectification Ratio between Different Number of Layers Structures



Triple > Double
> Single

$$A_r^{(3)} \sim \left[A_r^{(1)} \right]^3$$

Summary



- The rectification of nano/micro-swimmers in a system with asymmetric barriers is investigated by DPD simulations which take into account hydrodynamic effects.
- The rectification mechanism can be clearly identified: geometry-assisted diffusion and trap-hindered diffusion.
- Various barrier shapes are considered and the open circular barrier has the best performance while the V-shape one has the worst.
- Rectification efficiency of nano/microswimmers can be dramatically enhanced by a multi-layers of barriers.